Program Book





SANTANDER EXHIBITION CENTER

JUNE 6TH - 9TH 2011

Oceaus of Energy for a Sustainable Future







Local Organizers:



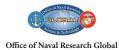


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NOTES

		Assembly Room	Room 1 (Bahía Hall)	Room 2A (Bahía Hall)	4-Room 3B (Bahía Hall)	5-Room 4B (Bahía Hall)	Room 5 (Bahía Hall)	Room 3A (Bahía Hall)	EXHIBITION & POSTERS	
9th	9:00 am to 1:00 pm		TUTORIAL T1: Ocean Observatories: A multichalenge to Survey Earth Environmental Process		TUTORIAL T2: AUV Technology and Application Basics		TUTORIAL T3: Signal Waveform Design for Underwater Acoustic Communications			
June 6	11:00 am	Morning Break								
Monday, Ju	3:00 pm to 7:00 pm		TUTORIAL T1: Ocean Observatories: A multichalenge to Survey Earth Environmental Process	TUTORIAL T6: The Stochastic Matched Filter and its Applications to Detection and Denoising			TUTORIAL T5: Technologies for Monitoring Marine Organisms and Hazards			
	5:00 pm				Afternoo	on Break				
	7:00 pm									
	8:00 pm	Welcome Reception, Magdalena Palace								

		Assembly Room	Room 1 (Bahía Hall)	Room 2A (Bahía Hall)	4-Room 3B (Bahía Hall)	5-Room 4B (Bahía Hall)	Room 5 (Bahía Hall)	Room 3A (Bahía Hall)	EXHIBITION & POSTERS			
	8:00 am		Registration									
	9:00 am	Plenary Session										
	10:45am	Opening Ceremony										
	11:30 am				Morning Brea	ık (exhibit hall)						
ne 7 th	12:00 am to 1:30 pm	Marine Renewable Energy - 1	Automatic Control	Climate Change	Sonar and Transducers	Vehicle Design I	Sonar Signal Processing					
y, Ju	1:30 pm				Lu	nch						
Tuesday, June	3:00 pm to 4:30 pm	Marine Renewable Energy - 2	Pollution Monitoring and Oil Spills	Offshore Structures	Sound Propagation & Scattering	Vehicle Design II	Array Signal Processing, Array Design and Vector Sensor Processing					
	4:30 pm	Afternoon Break										
	5:00 pm to 6:30 pm	Marine Renewable Energy - 3	Buoy Technology and Cables and Connectors	Hydrography	Underwater Acoustics & Acoustical Oceanography	Vehicle Performance	Model-Based Signal Processing Techniques					
	6:30 pm	Exhibitor's Reception										

		Assembly Room	Room 1 (Bahía Hall)	Room 2A (Bahía Hall)	4-Room 3B (Bahía Hall)	5-Room 4B (Bahía Hall)	Room 5 (Bahía Hall)	Room 3A (Bahía Hall)	EXHIBITION & POSTERS		
	9:00 am to 11:00 am	Marine Renewable Energy - 4	Ocean Dynamics: Wind, Waves, Surge and Sea Level	Ocean Data, Modeling and Information Management	Optics, Imaging, Vision and E-M Systems	Vehicle Navigation I	Sonar Imaging, Synthetic Aperture, Classificarion and Pattern Recognition I				
ıe 8 th	11:00 am				Mornin	g Break					
Wendsday, June 8 th	11:30 am to 1:30 pm	Marine Renewable Energy - 5 MAREN	Coastal Hydrodynamics	Coastal Engineering and Estuarine Systems	Optical Sensors, Marine Optics Technology and Instrumentation	Vehicle Navigation II	Acoustic Telemetry and Communication I	Sonar Imaging, Synthetic Aperture, Classification and Pattern Recognition I			
3	1:30 pm				Lur	nch					
	3:00 pm to 4:30 pm	Marine Renewable Energy - 6	European Projects on Underwater Networks -1	Oceanography: Physical, Chemical and Biological	3D Imaging and Holo- graphy	Autonomous Un- derwater Vehicles I	Acoustic Telemetry and Communication II				
	4:30 pm	Afternoon Break									
	5:00 pm to 6:30 pm	Marine Renewable Energy - 7	European Projects on Underwater Networks -2	Marine Law, Management and Safety	Oceanographic Instrumentation, Sensors and Current Measurement Technology I	Autonomous Underwater Vehicles II	Acoustic Telemetry and Communication III				
	21:00 pm		Gala Dinner, Gran Casino of Santander								

		Assembly Room	Room 1 (Bahía Hall)	Room 2A (Bahía Hall)	4-Room 3B (Bahía Hall)	5-Room 4B (Bahía Hall)	Room 5 (Bahía Hall)	Room 3A (Bahía Hall)	EXHIBITION & POSTERS
y, June 9 th	9:00 am to 11:00 am	Marine Communications and Technology I	European Projects on Underwater Networks -3	Coastal Radars and Passive Observing Sensors	Oceanographic Instrumentation, Sensors and Current Measurement Technology II	Systems and Observatories I	Acoustic Telemetry and Communication IV		
Thursday,	11:00 am	Morning Break							
Ē	11:30 am to 1:30 pm	Marine Communications and Technology II		Airborne and Satellite Radar, SAR and Space Systems	Other	Systems and Observatories II	Acoustic Telemetry and Communication V	Oceanographic Instrumentation, Sensors and Current Measurement Technology III	

WELCOME LETTER FROM CO-CHAIRS

On behalf of the Local Organising Committe for the Oceans '11 IEEE/ OES Conference and Exhibition, it is our pleasure to warmly welcome you to Santander and Cantabria. We are honoured to host the prestigious OCEANS series for the first time in Spain in a venue close to the ocean, the main link bringing together representatives from universities, industry and government organizations to update us on the most recent advances in ocean sciences and engineering.

Oceans'11 is also an excellent opportunity to showcase the vision of Santander and Cantabria, their historical ties to the Sea and the firm belief that a sustainable socio-economic development can be achieved through the use of renewable marine energy, guaranteeing the preservation of our world for future generations as is perfectly reflected in our conference slogan "Oceans of Energy for a Sustainable Future".

An opportunity for knowledge exchange, building of technical skills and expanding of professional networks has been planned thanks to an extensive programme including: first class tutorials, unique plenary sessions and an international and broad spectrum of technical sessions covering most of the relevant topics in the field. Moreover, you will have the opportunity to become acquainted with cutting edge products and services in our comercial exhibit.

But we will also have time to enjoy thanks to our social events and our beautiful city. Warm people, wonderful food and magnificent landscapes, mountains and beaches make Santander and Cantabria a beatiful location not to forget and surely to come back.

We'll do our best to make sure that you enjoy the conference and our city!

Iñigo J. LosadaConference Co-chair

Juan Pérez-Oria
Conference Co-chair

USEFUL INFORMATION

Conference Venue

The Convention Centre is a modern building located between the city centre and El Sardinero, a privileged spot surrounded by restaurants, hotels and beaches and with spectacular views overlooking the Cantabrian Sea. The different rooms will hold both the parallel sessions of the Conference and the commercial exhibition.

Visit www.oceans11ieeesantander.org

for additional information on the conference and Trade Center.

Palacio de Exposiciones y Congresos de Santander

Avda. del Stadium, s/n 39005 Santander - Cantabria

Phone: +34 942318180

Parking Facilities

There is a free parking available opposite the Convention Center. It belongs to the Football Stadium but you can freely park there at any time except trucks, mobile-homes or campers which are not allowed. The main entrance of the Convention Center is located in front of the parking overlooking the Stadium.

Transportation Information

Buses to the airport with the "Alsa Company" depart every half an hour from Santander bus station which is located in the heart of the city in "Plaza de las Estaciones". The same is applied for the arrivals, the buses leave the airport at quarter past and quarter to and drops you off there.

To move from the city centre to the Sardinero area where the Convention Center is and the majority of hotels are located, there are several public buses available (lines number 1, 2, 3, 4, 5, 6 and 7) in different stops in the city. There is an exception for the Hotel Real because the only bus that stops there is line number 5.

General Area Information

International Calling Code for Spain: 0034

Local Currency: Euro **Language:** Spanish

Weather in June: Average temperature is 16° C

Average Precipitation: 65 mm.

Time Zone: Europe

CONFERENCE INFORMATION

On Site Registration

On Site registration for Oceans 2011 will be available in the Santander Convention Center's Lobby. Registration hours are:

Day	Time
Monday, June 6	3:00 pm — 7:00 pm
Tuesday, June 7	8:00 am — 6:30 pm
Wednesday, June 8	9:00 am — 6:30 pm
Thursday, June 9	9:00 am — 2:00 pm

Tutorials

Day	Time
Monday, June 6	9:00 am — 1:00 pm & 3:00 pm — 7:00 pm

Exhibit Hall Hours

Day	Time
Tuesday, June 7	9:00 am — 6:30 pm
Wednesday, June 8	9:00 am — 6:30 pm
Thursday, June 9	9:00 am — 2:00 pm

Technical Session Hours

Technical Sessions are scheduled for Tuesday, June 7, Wednesday, June 8 and Thursday, June 9 during the following hours:

Day	Time
Tuesday, June 7	9:00 am — 6:30 pm
Wednesday, June 8	9:00 am — 6:30 pm
Thursday, June 9	9:00 am — 2:00 pm

Student Poster Hours

Day	Time
Tuesday, June 7	9:00 am — 6:30 pm
Wednesday, June 8	9:00 am — 6:30 pm
Thursday, June 9	9:00 am — 2:00 pm

Luncheons

Tuesday, June 7, 1:30 pm -3:00 pm

Wednesday, June 8, 1:30 pm − 3:00 pm

Social Events

Welcome cocktail, Magdalena Palace

Monday, June 6, 8:00 pm - 9:00 pm

Exhibitor's Reception, Santander Convention Center, Oceans 2011

Exhibit Hall

Tuesday, June 7, 6:30 pm

Oceans 2011 Gala Reception, Gran Casino of Santander,

Plaza de Italia, s/n, Santander

Wednesday, June 8, 9:00 pm

Internet Area

There will be four computers and a printer available for all delegates at the commercial exhibition area.

Internet Access

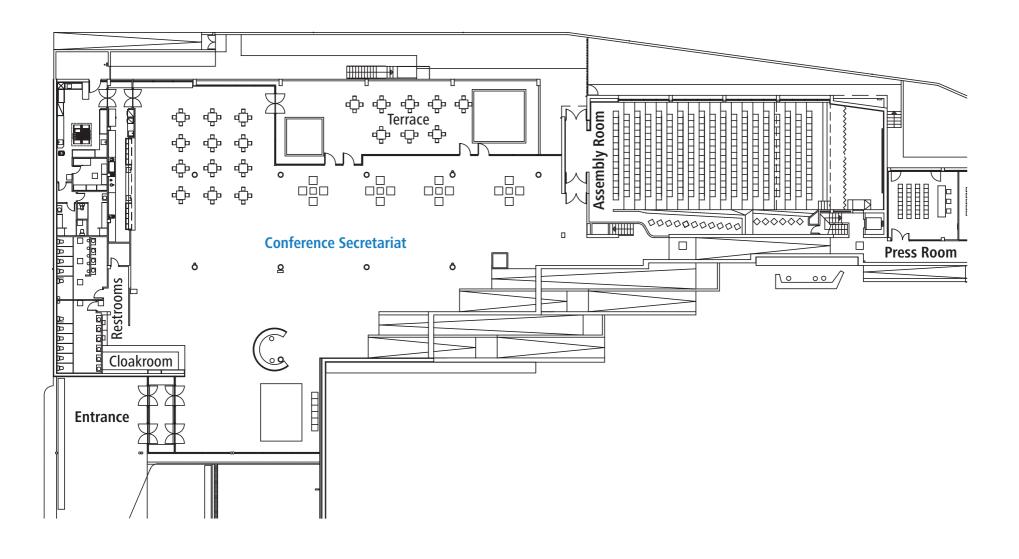
Wireless is provided throughout the Convention Center for your convenience.

A username and a password will be provided upon registration along with the rest of documentation.

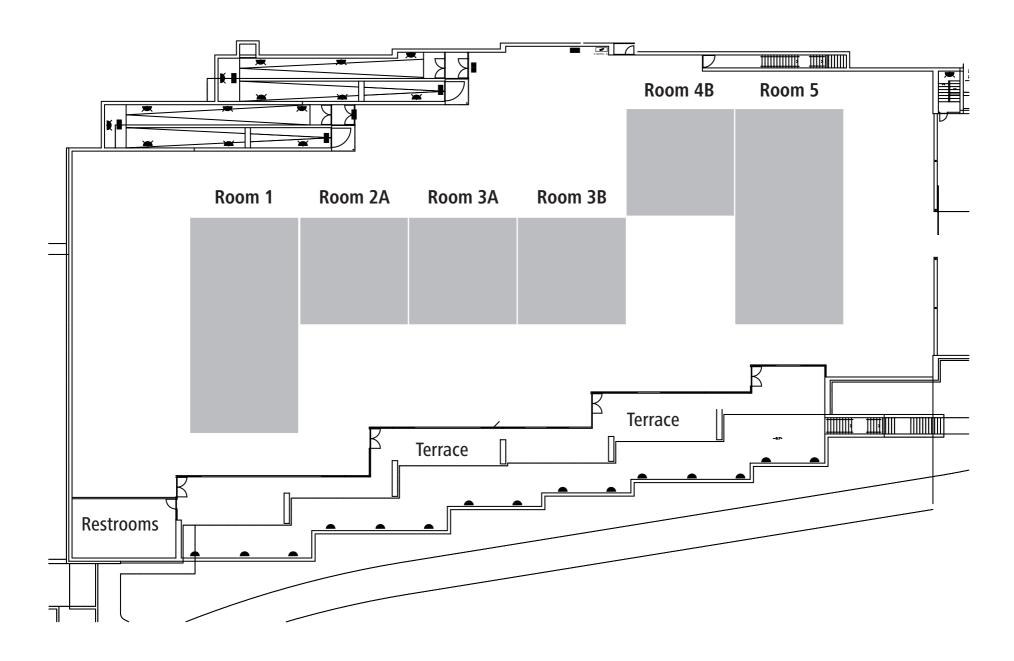
Unauthorized Audio/Video Recording

Unauthorized Audio/Video Recording of tutorials, plenary, or technical sessions is not permitted.

MAIN FLOOR Santander Convention Center



2nd FLOOR (Sala Bahía) Santander Convention Center



PLENARY SPEAKER PROFILES



Dr. Edoardo Bovio

Dr. Edoardo Bovio (Italy), after graduation in Electrical Engineering at the University of Genoa in 1976, joined the SHAPE Technical Centre in The Hague where he worked in communications and radar. From 1979 to 1980 he worked for Hewlett Packard specializing in engineering applications of signal processing techniques.

Since 1980 he is with the NATO Undersea Research Centre (NURC). Until 1987 he led the development of low frequency active sonar systems. From 1987 to 1997 he has been responsible for the computer department. From 1997 to 2007 he has been in charge of the Centre's Autonomous Underwater Vehicle (AUV) program. This work evolved from basic research on vehicle technology in collaboration with many research institutions and NATO Navies, to focused studies that quantify the benefits of AUVs for military and civilian applications, with special emphasis on harbor protection. In the period 2003-2007 Dr. Bovio has organized and conducted trials in Italy, Scotland, Germany, Netherlands, Bulgaria and Estonia obtaining a comprehensive data base from the best commercially available AUVs. The analysis of this data is important for 'quantifying' system performance in a variety of scenarios. Dr. Bovio has published more than 20 papers on the applications of autonomous underwater vehicles.

Following the introduction of the Customer Work Program in 2007 and the approval of NURC hybrid funding, Dr. Bovio has been appointed NURC Business Development Manager. Since March 2011 Dr. Bovio is the acting Chief Scientist at NURC.

PLENARY SPEAKER PROFILES



Dr. Luis Valdés Santurio

Dr. Luis Valdés Santurio (Spain) is the Head of Ocean Sciences at the Intergovernmental Oceanographic Commission of UNESCO since January 2009, and formerly (2000-2008) he has been the Director of the Centro Oceanográfico de Gijón - Instituto Español de Oceanografía (CO Gijón-IEO). With more than 30 years of experience in marine research and field studies related with mari-

ne ecology and climate change, he established in 1990 the time series programme based on ocean sampling sites and marine observatories which is maintained by Spain in the North Atlantic and the Mediterranean Sea (www.seriestemporales-ieo.net). This program has been a pioneer and successful initiative in Spain; it represents a significant contribution to the understanding of our marine environment and is a good example on the importance of the basic research as an essential tool for a responsible management of natural resources. Dr. Valdés has advised various governmental, intergovernmental and international organizations as well as research funding agencies. He was appointed by the Government of Spain as the Spanish Delegate in the IOC-UNESCO as well as in the International Council for the Exploration of the Sea (ICES), where he has chaired different groups and committees including the Oceanographic Committee and the Steering Group on Climate Change. With the support of IOC, ICES and other councils he has served as convener at several International Symposia and was also the local organizer of the Symposium on the Effects of Climate Change in the World's Oceans (Gijón, 2008). In 2007 he got the ICES Services award and has also received other national and international recognitions.

oceans 2011 IEEE/OES Santander, Spain

KEY NOTE SPEECHES

Title: Autonomous persistent surveillance of the ocean for

military and civilian applications

Date:Tuesday, June 7Time:09,00-09,20hLocation:Room 108

Summary: Pragmatic calculations using true time and space scales of ocean properties and the real cost and complexity of in-situ observations clearly indicate that the parameters required to take correct decisions and actions are very often insufficiently sampled both in time and in space. Yet decision makers are faced with increasing pressure by the public opinion to preserve the environment and at the same time support the economic development of coastal areas, all to be achieved in times of declining budgets. This justifies the need for cost effective systems that provide the information required to take environmentally conscious decisions and actions.

The scientific community has addressed this problem since the early nineties with the development of new tools and methodologies to address the spare sampling problem and reduce errors in ocean field estimations to enable definitive hypothesis testing. Of particular relevance in this context are the Autonomous Ocean Sampling Network (AOSN) and the Persistent Littoral Surveillance Network (PLUSNet) initiatives that studied and developed multiple mobile sensors to resolve synoptic fields and spatial gradients to a desired level of precision.

Technology has evolved and several systems and subsystems are now available that contribute to improve ocean understanding. In the past decade, the NATO Undersea Research Centre has been active in the development of autonomous systems for the persistent surveillance of the ocean. This presentation describes the work done at NURC and presents examples of military and civilian applications."

Title: Oceans in Focus: Science and Governance

for Global Sustainability

Date: Tuesday, June 7
Time: 09,25-10,40h
Location: Room 108

Summary: Public awareness about environmental problems has increased considerably in the last years, so that societies are now demanding from policymakers proactive positions towards respecting the sustainable use and management of natural resources and mitigate the impacts of global change (e.g. UNCSD Rio+20). In the next 10 years, social pressure will probably encourage policymakers to reach agreements regarding limits on carbon emissions and set up planetary boundaries for other anthropogenic impacts. In some cases, these new approaches are already being implemented in common marine strategies at regional and international levels, which will demand considerable efforts towards increasing oceanographic data acquisition, and towards promoting data analysis and technological assistance. Hopefully these approaches will deepen our understanding of the role the ocean dynamics have in the functioning of the Earth System, in climate change and in the sustainability of life on earth, which will define the conditions for scientist to prepare accurate scenarios for future

Firstly, more and new research has to be done to fully understand and evaluate the impacts of global change on the World's oceans. There is a general agreement that our understanding of the role the oceans play in modulating the climate and ecology of the planet needs to be improved. For example, the experts claim for an evaluation of the economic and social dimension of ocean acidification and warming, which are the two main effects of climate change in the oceans, but also the lost of biodiversity is now seen as a risk for the ecosystem resilience and other ecosystem services. To achieve the needed knowledge will require research at unprecedented geographic scales. Obtain data with a better spatial and temporal resolution is a crucial and necessary step to take the pulse of the oceans at a planetary scale and then keep them under permanent review.

Secondly, it has to be mentioned that the governance of oceans is fragmented (fishing, shipping, offshore oil and gas, offshore renewable energy, etc) as if we were managing separate entities. There is an urgent necessity for an international framework of cooperation

for both ocean research and governance. Uses of the ocean, as well as climate change and biodiversity are global problems, and its management cannot depend solely in the sovereignty of single states. Several international instruments have been agreed in the past as a foundation to redress these problems, including the United Nations Convention on the Law of the Sea; the London Convention on Marine Pollution; the Code of Conduct for Responsible Fisheries; the Convention on Ballast Water; the Convention on Biological Diversity, as well as several international plans of action. The success of these international instruments, which contain commitments to reduce the human impact on the ocean and marine ecosystems depends heavily on the decision of governments and states; and multilateral organizations such as the UN agencies plays a decisive role in making this governance a reality.

TUTORIALS

All Oceans 2011 Santander tutorials will take place on Monday June 6. Full day and morning sessions begin at 09,00h. Half-day sessions that are scheduled for the afternoon begin at 15,00h. For description of these tutorials, please visit: http://www.oceans11ieeesantander.org/main.cfm/EID/22/Tutorials/

T1. Ocean observatories:

A multichallenge to survey earth environmental process.

Instructor: Juanjo Dañobeitia (Profesor in Marine Geophysics. Spanish Research Council (CSIC). Director of Marine Technological Unit (UTM) Barcelona, Spain) and Jordi Sorribas (Marine Geologist. Spanish Research Council (CSIC). Head of Telematics Group of Marine Technological Unit (UTM) Barcelona, Spain).

Session Time: 9:00 am to 1:00 pm & 3:00 pm to 7:00 pm

Location: Room 1

T2. AUV technology and application basics.

Instructor: William J. Kirkwood (Senior Research and Development Engineer at the Monterey Bay Aquarium Research Institute (MBARI) Monterey Bay, California). USA.

Session Time: 9:00 am to 1:00 pm

Location: Room 3B

T3. Signal waveform design for underwater acoustic communications.

Instructor: Charalampos C. Tsimenidis (Senior Lecturer in Signal Processing for Communications in the School of Electrical, Electronic, and Computer Engineering) and Bayan S. Sharif (Professor of Digital Communications and Head of the School of Electrical, Electronic and Computer Engineering).

Newcastle University. UK.

Session Time: 9:00 am to 1:00 pm

Location: Room 5

T5. Technologies for monitoring marine organisms and hazards.

Instructor: Jaume Piera (B.S. in Telecommunications Engineering, Technical University of Catalonia, 1991).

university of Catalonia, 1991).

Session Time: 3:00 pm to 7:00 pm

Location: Room 5

T6. The stochastic matched filter and its applications to detection and denoising.

Instructor: Philippe Courmontagne (Professor in the Institut Supérieur de

l'Électronique et du Numérique, ISEN Toulon, France).

Session Time: 3:00 pm to 7:00 pm

Location: Room 2A

STUDENT POSTERS

Exhibit Hall

High performance underwater UHF radio antenna development.

Hector Fabian Guarnizo Mendez (France).

A comparison between the classical pulse compression and the improved WV-SMF-PC on ifremer sea trials signals.

Gregory Julien (France).

Tuning the performance of the superdirective frequency-invariant beamforming applied to end-fire arrays.

Federico Traverso (Italy).

Passive acoustic detection of a small remotely operated vehicle.

Meng Cai (USA).

Unnamed localization of sperm whales in realistic scenarios.

Pablo Caro (Spain).

A heterogeneous rapid-turnaround visualization package for AUV Data.

Mark VanMiddlesworth (USA).

Near sea surface target tracking by extended Kalman filtering of the GPS reflected signals.

Sarab Tay (France).

Doppler effect on bathymetry using frequency modulated multibeam echo sounders.

Pauline Vincent (France).

Design and development of a distributed wave energy converter.

Pierre Garambois (France).

Dynamics of the turbidity plume in the Guadalquivir estuary (SW Spain): A remote sensing approach.

Isabel Caballero (Spain).

Using slocum gliders for coordinated spatial sampling.

Hans Christian Woithe (USA).

A multivariate approach to estimate design loads for offshore wind turbines. Yanira Guanche (Spain).

 $\label{thm:continuous} \mbox{Optimal trajectory generation for draped AUV gravity surveys.}$

Jacob Izraelevitz (USA).

Ocean wave observation by GPS signal.

Jian Cui (Japan).

Implementation of embedded system for autonomous buoy. Kyung Woon Lee (Korea).

Blind source separation of non-linearly mixed ocean acoustic signals using slow feature analysis.

Suraj Kamal (India).

JUNIOR WORKSHOP

A workshop and competition in the design of autonomous devices will be held the week before the Conference. Several High School teams will attend this workshop. A competition showing the works they have developed will take place last Saturday of May in the School of Nautical Studies and the CEAR (Specialized Centre of High Performance) for sailing (RFEV, Royal Spanish Sailing Federation). In a small water storage pond each team will have to complete a mission rescuing a boat with a personalized and programmed autonomous device. Awards for the best performances and originality of works will be given in the Conference.

JUNIOR WORKSHOP SPONSORS

Ayuntamiento de Camargo Ayuntamiento de Astillero Caja Cantabria Taller Cobo Hermanos S.L.

STUDENT POSTER COMPETITION

Exhibition & Posters

Optimal trajectory generation for draped auv gravity surveys

Jacob Izraelevitz, Franklin W. Olin College of Engineering

A multivariate approach to estimate design loads for offshore wind turbines

Yanira Guanche, "IH Cantabria", Universidad de Cantabria Raúl Guanche, "IH Cantabria", Universidad de Cantabria Paula Camus, "IH Cantabria", Universidad de Cantabria Fernando Mendez, "IH Cantabria", Universidad de Cantabria Raúl Medina, "IH Cantabria", Universidad de Cantabria

Using slocum gliders for coordinated spatial sampling

Hans Woithe, *Rutgers University* Ulrich Kremer, *Rutgers University*

A comparison between the classical pulse compression and the improved WV-SMF-PC on Ifremer sea trials signals

Gregory Julien, IFREMER
Philippe Courmontagne, IM2NP/ISEN-Toulon
Marie-Edith Bouhier, IFREMER

Dynamics of the turbidity plume in the Guadalquivir estuary (SW Spain): a remote sensing approach

Isabel Caballero, *Instituto de Ciencias Marinas Andalucía, CSIC* Javier Ruiz, *ICMAN-CSIC* Gabriel Navarro, *Instituto de Ciencias Marinas Andalucía, CSIC*

Implementation of embedded system for autonomous buoy

Kyung Woon Lee, Korea University
Jung Ho Park, Korea University
Dong-ho Lee, Korea University
Ui-seok Jeong, Korea University
Ho Kyung Jun, Shinyang Technology
Joon Young Yang, Korea University

Design and development of a distributed wave energy converter

Jacob Foster, *U of Hawaii*Pierre Garambois, *University of Hawaii (Mechanical Engineering)*Reza Ghorbani, *U of Hawaii*

Monitoring species using acoustic communications

David Gandul, UPC-SARTI
Erik Molino-Minero-Re, Universidad Politecnica Catalunya
Antoni Manuel, Universidad Politécnica de Cataluña
Joaquín del Río, Universidad Politécnica de Cataluña
Francesc Sarda, Institut de Ciencies del Mar
Jacopo Aguzzi, Institut de Ciencies del Mar
Guiomar Rollant, Institut de Recerca i Tecnologia Agroalimentaries

Blind source separation of non-linearly mixed ocean acoustic signals using slow feature analysis

Suraj Kamal, Cochin *University of Science And Technology*Supriya H, Cochin *University of Science And Technology*P R SASEENDRAN PILLAI, *Cochin University of Science And Technology*

Doppler effect on bathymetry using frequency modulated multibeam echo sounders

Pauline Vincent, Telecom Bretagne Frédéric maussang, Telecom Bretagne Xavier Lurton, IFREMER René Garello, Telecom Bretagne Christophe Sintes, Telecom-Bretagne

A Heterogeneous Rapid-Turnaround Visualization Package for AUV Data Mark VanMiddlesworth, *Harvard University*

Ocean wave observation by GPS signal

Jian Cui, Kobe University, *Graduate School of Maritime Sciences* Nobuyoshi Kouguchi, *Kobe University, Faculty of Maritime Sciences*

Unmanned localization of sperm whales in realistic scenarios

Pablo Caro, *Universidad Politecnica de Madrid* Antonio Silva, *ISR - Universidade do Algarve*

Passive acoustic detection of a small remotely operated vehicle

Meng Cai, *University of Hawaii at Manoa* Brian Bingham, *University of Hawaii at Manoa*

Near sea surface target tracking by extended kalman filtering of the GPS reflected signals

Sarab Tay, *Télécom Bretagne* Frederic Maussang, *Telecom Bretagne*

Arnaud Coatanhay, ENSTA Bretagne Thierry Chonavel, Télécom Bretagne Rene Garello, Telecom Bretagne

Tuning the performance of the superdirective frequency-invariant beamforming applied to end-fire arrays

Federico Traverso, Department of Biophysical and Electronic Engineering, University of Genoa

Marco Crocco, Italian Institute of Technology (IIT), Genoa, Italy Andrea Trucco, Department of Biophysical and Electronic Engineering, University of Genoa

Gianni Vernazza, Department of Biophysical and Electronic Engineering, University of Genoa

High performance underwater UHF radio antenna development

Hector Fabian Mendez, *Telecom - Bretagne / Ifremer / Lab-STICC*François Le Pennec, *Telecom Bretagne / Lab-STICC*Christian GAC, *IFREMER*Christian Person, *Telecom Bretagne / lab-STICC*

TECHNICAL PROGRAM

Monday, June 6

TUTORIAL T1: Ocean Observatories: A multichalenge to survey earth environmental process

2-Room 1 (Bahía Hall)

Monday, June 6 (9:00AM - 1:00PM) (3:00PM - 7:00PM)

Juanjo Dañobeitia and Jordi Sorribas

TUTORIAL T2: AUV technology and application basics

4-Room 3B (Bahía Hall)

Monday, June 6 (9:00AM - 1:00PM)

William J. Kirkwood

TUTORIAL T3: Signal waveform design for underwater acoustic communications

6-Room 5 (Bahía Hall)

Monday, June 6 (9:00AM - 1:00PM)

Charalampos C. Tsimenidis and Bayan S. Sharif

TUTORIAL T5: Technologies for monitoring marine organisms and hazards

6-Room 5 (Bahía Hall)

Monday, June 6 (3:00PM - 7:00PM)

Jaume Piera

TUTORIAL T6: The Stochastic Matched Filter and its applications to detection and denoising

3-Room 2A (Bahía Hall)

Monday, June 6 (3:00PM - 7:00PM)

Philippe Courmontagne

TECHNICAL PROGRAM

Tuesday, June 7

Marine Renewable Energy - 1

1-Assembly Room

Tuesday, June 7 (12:00AM - 1:30PM)

Chair: Cesar Vidal, IH Cantabria, Universidad de Cantabria

Ocean radar for the planning and operational phase of off-shore renewable energy systems

Thomas Helzel, *Helzel Messtechnik GmbH* Oswaldo López, *Innova Ocanografia Litoral* Lucy Wyatt, *Seaview Sensing Ltd*.

Estimation of the electric power potential using pressure retarded osmosis in the Leon River's mouth: a first step for the harnessing of saline gradients in Colombia

Oscar Alvarez, Universidad Nacional de Colombia Andrés Osorio, Universidad Nacional de Colombia Santiago Ortega, Universidad Nacional de Colombia Pablo Agudelo, Universidad Nacional de Colombia

Methodology for estimating wave power potential in places with scarce instrumentation in the Caribbean Sea

Santiago Ortega, *Universidad Nacional de Colombia - Sede Medellín* Andres Osorio, *Universidad Nacional de Colombia - Sede Medellín* Pablo Agudelo-Restrepo, *I Consult S.A.* Jaime Velez. *Universidad Nacional de Colombia - Sede Medellín*

Model-based global assessment of OTEC resource with data validation in south florida

Lindy Rauchenstein, Florida Atlantic University James VanZwieten, Florida Atlantic University Howard Hanson, Florida Atlantic University

Evaluation of global wave energy resources

Borja Reguero, IH Cantabria, Univ. de Cantabria Melisa Garcia, IH Cantabria, Univ. de Cantabria Fernando Incera, IH Cantabria, Univ. de Cantabria Roberto Solana, IH Cantabria, Univ. de Cantabria Iñigo Rodriguez, IH Cantabria, Univ. de Cantabria Cesar Vidal, IH Cantabria, Univ. de Cantabria

Automatic Control

2-Room 1 (Bahía Hall)

Tuesday, June 7 (12:00AM - 1:30PM)

Co-Chairs: Fredrik Dukan, Norwegian University of Science and Technology
Juan Perez-Oria, University of Cantabria

Dynamic positioning system for a small size ROV with experimental results

Fredrik Dukan, Norwegian University of Science and Technology Martin Ludvigsen, Norwegian University of Science and Technology Asgeir Sørensen, Norwegian University of Science and Technology

Long term power management in sailing robots

Colin Sauze, Department of Computer Science, Aberystwyth University Mark Neal, Department of Computer Science, Aberystwyth University

Coordinated sea rescue system based on unmanned air vehicles and surface vessels

Francisco Fernández Ramírez, *Universidad Complutense de Madrid*David Sánchez Benitez, *Universidad Complutense de Madrid*Eva Besada Portas, *Universidad Complutense de Madrid*Jose Antonio López Orozco, *Universidad Complutense de Madrid*

Parameter estimation of ship linear manoeuvring models

Elías Revestido, *Univ. Cantabria* Francisco J Velasco, *Univ. Cantabria* Eloy López, *Univ. Pais Vasco* Emiliano Moyano, *Univ. Cantabria* Isabel Zamanillo, *Univ. Cantabria*

Climate Change

3-Room 2A (Bahía Hall)

Tuesday, June 7 (12:00AM - 1:30PM)

Chair: Alicia Lavín, Instituto Español de Oceanografía

Impacts of land use and climate change on hydrologic processes in shallow aquatic ecosystems

Clarisse Betancourt, University of Puerto Rico- Rio Piedras Campus Maury Estes, Universities Space Research Association Mohammad Alhamdan, Universities Space Research Association

Does concern for global warming explain support for wave energy development? A case study from Oregon, U.S.A

Maria Stefanovich, OSU

The Spanish Institute Of Oceanography (IEO) Santander observing system

Alicia Lavín, Instituto Español de Oceanografía
Carmen Rodriguez, IEO
César González-Pola, Instituto Español de Oceanografía
Raquel Somavilla, Instituto Español de Oceanografía
Maria Jesús García, Instituto Español de Oceanografía
Elena Tel, Instituto Español de Oceanografía
Daniel Cano, Instituto Español de Oceanografía
Jesús Carranza, Instituto Español de Oceanografía
Angel Merino, Instituto Español de Oceanografía
Amaia Villoria, Instituto Español de Oceanografía
Elena Marcos, Instituto Español de Oceanografía

Joaquín Molinero, *Instituto Español de Oceanografía* Carlos Barrera, *Plataforma Oceánica de Canarias (PLOCAN)*

Data, knowledge, and innovation

James Marsh, Shidler College of Business

Sonar and Transducers

4-Room 3B (Bahía Hall)

Tuesday, June 7 (12:00AM - 1:30PM)

Chais: Rajapan Dhilsha, National Institute of Ocean Technology

A wide angle shallow water observing sonar

John Atkins, *University of Auckland* Jeremie Barrel, *Industrial Research Limited* Neil Scott, *Industrial Research Limited* Eugene Stytsenko, *Industrial Research Limited*

Effect of manufacturing procedure on the miniaturized flextensional transducers (Cymbals) and hydrophone array performance

Chandrabose Kannan, *National Institute of Ocean Technology*Madava Rao Rajeshwari, *National Institute of Ocean Technology*Jacob Shibu, *National Institute of Ocean Technology*Amrithalingam Malarkkodi, *National Institute of Ocean Technology*Rajapan Dhilsha, *National Institute of Ocean Technology*M. Aravindakshan Atmanand, *National Institute of Ocean Technology*

Estimated flow noise levels due to a thin line digital towed array

Unnikrishnan Kuttan Chandrika, Acoustic Research Laboratory, Tropical Marine Science Institute, National University of Singapore

Venugopalan Pallayil, Acoustic Research Laboratory, Tropical Marine Science Institute, National University of Singapore

Mandar Chitre, Acoustic Research Laboratory, Tropical Marine Science Institute, National University of Singapore

Subash Kuselan, Acoustic Research Laboratory, Tropical Marine Science Institute, National University of Singapore

Underwater multi-frequency transmitter for seabed characterization

Lucilla Di Marcoberardino, *Institut Jean Le Rond d'Alembert*Jacques MarchaL, *Institut Jean Le Rond d'Alembert*Pierre Cervenka, *Institut Jean Le Rond d'Alembert*

Vehicle Design I

5-Room 4B (Bahía Hall)

Tuesday, June 7 (12:00AM - 1:30PM)

Co-Chairs: David Ribas, *Universitat de Girona* Vincenzo Calabro , *University of Pisa*

Design of a CMG for underwater robots

Eugenio Yime, *Universidad Tecnologica de Bolivar*Héctor Moreno, *Centre for Automation and Robotics, UPM-CSIC*Roque Saltaren, *Center for Automation and Robotics, UPM-CSIC*.
Rafael Aracil, *Center for Automation and Robotics, UPM-CSIC*.

Kinematic analysis of an underwater parallel robot

Héctor Moreno, Centre for Automation and Robotics, UPM-CSIC Lisandro Puglisi, Center for Automation and Robotics, UPM-CSIC. Roque Saltaren, Center for Automation and Robotics, UPM-CSIC. Isela Carrera, Center for Automation and Robotics, UPM-CSIC.

Design and construction of the GUANAY-II autonomous underwater vehicle

Julián González, Universidad Politécnica de Cataluña Spartacus Gomáriz, Universidad Politécnica de Cataluña Jordi Prat, Universidad Politécnica de Cataluña Gerard Masmitja, Universidad Politécnica de Cataluña Iván Masmitja, Universidad Politécnica de Cataluña Alejandro Arbos, Universidad Politécnica de Cataluña

Lagrangian modeling of the Underwater Wave Glider

Andrea Caiti, *Dep. of Energy and Systems Engineering*Vincenzo Calabrò, *Dep. of Energy and Systems Engineering*Andrea Munafò, *Integrated Systems for Marine Environment*Sergio Grammatico, *Dep. of Energy and Systems Engineering*Mirko Stifani, *Italian Navy (CSSN) Department*

The Girona 500, a multipurpose autonomous underwater vehicle

David Ribas, *Universitat de Girona*Pere Ridao, *Universitat de Girona*Lluís Magí, *Universitat de Girona*Narcis Palomeras, *Universitat de Girona*Marc Carreras. *Universitat de Girona*

Sonar Signal Processing

6-Room 5 (Bahía Hall) Tuesday, June 7 (12:00AM - 1:30PM)

Chair: Jean-Pierre Hermand, Environmental Hydroacoustics Lab

Interferometric angle estimation for bathymetry performance analysis

Gerard Llort-Pujol, *Télécom Bretagne* Christophe Sintes, *Télécom Bretagne*

A new method for 3D localization using a hybrid array in shallow ocean with non-Gaussian noise

Zahra Madadi Ardekani, *Nanyang Technological University* Gargewari Anand, *Indian Institue of Science* Benjamin Premkumar, *Nanyang Technological University*

Multistatic adaptive active sonar signal processing

Jun Ling, *University of Florida* Jian Li, *University of Florida*

Doppler domain decomposition of the underwater acoustic channel response

Salman Ijaz, Institute of Systems and Robotics António Silva, Institute of Systems and Robotics Orlando Rodríguez, Institute of Systems and Robotics Sérgio Jesus, Institute of Systems and Robotics

Time and angle of arrival uncertainties in echo-sounding

Christian de Moustier, HLS Research, Inc.

Acoustic striation processing for ocean bottom characterization

Jean-Pierre Hermand, Environmental Hydroacoustics Lab Qunyan REN, Environmental Hydroacoustics Lab

Marine Renewable Energy - 2

1-Assembly Room

Tuesday, June 7 (3:00PM - 4:30PM)

Chair: Raúl Guanche, IH Cantabria, Univ. de Cantabria

Anchoring systems for marine renewable energies offshore platforms

Raul Arias, Fundacion Centro Tecnologico de Componentes

Iñaki Sanchez, Fundación Centro Tecnológico de Componentes

Cesar Pascual ,IH Cantabria, Univ. de Cantabria

Jorge Berini, Universidad de Cantabria. E.T.S. Ingenieros de Caminos. Dpto. Cien-

cia e Ingenieria del terreno y de los Materiales

Jose Angel Formoso, Universidade da Coruña.

Vicente Casas, Universidade da Coruña

Differences in fundamental design drivers for wind and tidal turbines

Alexei Winter, University of Bristol

Component failure simulation tool for optimal electrical configuration and repair strategy of off-shore wind farms

Roberto Minguez, *IH Cantabria, Univ. de Cantabria* José Martínez, *IH Cantabria, Univ. de Cantabria*

Omar Castellanos, IH Cantabria, Univ. de Cantabria

Raul Guanche, IH Cantabria, Univ. de Cantabria

IDERMAR METEO. Offshore wind assessment at high and very high water depths

Raúl Guanche, IH Cantabria, Univ. de Cantabria César Vidal, IH Cantabria, Univ. de Cantabria

Ángel Piedra, APIA XXI

Íñigo Losada, IH Cantabria, Univ. de Cantabria

Autonomous instrumentation system for offshore marine applications: metmast wind resource measurement implementation

Juan Echevarría, ACORDE Technologies S.A.

Álvaro Álvarez, ACORDE Technologies S.A. Joaquin Sañudo, ACORDE Technologies S.A. Jacobo Domínguez, ACORDE Technologies S.A. David Blanco, ACORDE Technologies S.A.

Pollution Monitoring and Oil Spills

2-Room 1 (Bahía Hall)

Tuesday, June 7 (3:00PM - 4:30PM)

Co-Chairs: Maria J San Jose, Universidad del Pais Vasco

Daura Vega Moreno, Instituto Canario de Ciencias Marinas

Towards automatic oil spill confinement with autonomous marine surface vehicles

Fernando Pereda, *Dept ACYA. Universidad Complutense de Madrid*Hector Garcia de Marina, *Dept ACYA. Universidad Complutense de Madrid*Jose Giron-Sierra, *Dept ACYA. Universidad Complutense de Madrid*Juan Jimenez, *Dept ACYA. Universidad Complutense de Madrid*

Early detection of hydrocarbons in the marine environment

Carlos Barrera, PLOCAN
Laura Cardona, ICCM
Maria Guadalupe Villagarcía, ICCM
Maria Jose Rueda, ICCM
Dolores Gelado, ULPGC
Octavio Llinás, PLOCAN
Daura Vega, ULPGC

Carolina Garcia, ICCM

Environmental impact assessment of Foz do Arelho sewage plume using MARES AUV

Patrícia Ramos, *INESC Porto* Nuno Abreu, *INESC Porto*

Chemical treatments against biofouling on industrial equipments associated to marine related power generation technologies, a new approaching to an old problem

Alfredo Ruiz, *Universidad de Cantabria*Emilio López, *Universidad de Cantabria*José Alberto Célis, *Universidad de Cantabria*Sergio Gómez, *Universidad de Cantabria*Andrés Abelleira, *Universidad de Cantabria*

Applicability of clean technology of conical spouted bed for thermal remediation of sand polluted by oil spill

Maria J San Jose, Universidad del Pais Vasco Sonia Alvarez, Universidad del Pais Vasco Luis B López, Universidad del Pais Vasco Iris García. Universidad del Pais Vasco

On the applications of a compact autonomous acoustic recorder

Cristiano Soares, MarSensing - Marine Sensing & Acoustic Technologies, Lda. Friedrich Zabel, MarSensing - Marine Sensing & Acoustic Technologies, Lda. Celestino Martins, MarSensing - Marine Sensing & Acoustic Technologies, Lda. António Silva, Universidade do Algarve

Offshore structures

3-Room 2A (Bahía Hall) Tuesday, June 7 (3:00PM - 4:30PM) Chair: Shinichi Takagawa, *University of Tokyo*

A study on high frequency hammering system and its impact loads? Second report

Shinichi Takagawa, University of Tokyo

Experimental study for wave induced hydraulic pressure subjected to bottom of floating structure

Youn-Ju Jeong, Korea Institute of Construction Technology Young-Jun You, Korea Institute of Construction Technology

Experimental study on hydrodynamic motion of hybrid type of pontoon

Youngjun You, Korea Institute of Construction Technology Youn-ju Jeong, Korea Institute of Construction Technology

Sound Propagation & Scattering

4-Room 3B (Bahía Hall)

Tuesday, June 7 (3:00PM - 4:30PM)

Chair: Ole Grøn, University of Southern Denmark

Iso-TL curve in multistatic configuration

Hisashi Shiba, NEC Corporation

A simulation analysis of large scale path loss in an underwater acoustic network

Jesus Llor, *Universidad Miguel Hernandez* Milica Stojanovic, *Northeastern University* Manuel Pérez Malumbres, *Universidad Miguel Hernandez*

Broadband amplitude and phase sonar calibration using LFM pulses for high-resolution study of hard and soft acoustic targets

Alan Islas-Cital, The University of Birmingham Philip Atkins, The University of Birmingham Kae Foo, The University of Birmingham Ruben Picó, Universitat Politecnica de Valencia

On the in-situ detection of flint for underwater Stone Age archaeology

Qunyan Ren, Environmental Hydroacoustics Lab Ole Gron, Langelands MuseumCenter for Maritime Archaeology Jean-Pierre Hermand, Environmental Hydroacoustics Lab

High transmission loss of slit arrays for underwater sound

Héctor Estrada, Centro de Tecnologías Físicas, Unidad Asociada ICMM- CSIC/UPV José María Bravo, Centro de Tecnologías Físicas, Unidad Asociada ICMM- CSIC/UPV Francisco Meseguer, Centro de Tecnologías Físicas, Unidad Asociada ICMM- CSIC/UPV

Modulation of a high-frequency shallow-water acoustic channel by sea surface waves: 3-D PE-based modeling

Wendell Saintval, *Naval Research Laboratory* Thomas Hayward, *Naval Research Laboratory*

Vehicle Design II

5-Room 4B (Bahía Hall)

Tuesday, June 7 (3:00PM - 4:30PM)

Chair: Kenichi Asakawa, Japan Agency for Marine-Earth Science and Technology

Experimental determination of the hydrofoil's angle of attack in the case of a turtle-like Autonomous Underwater Vehicle

Davinia Font, *Universitat de Lleida*Marcel Tresancez, *Universitat de Lleida*Cedric Siegenthaler, *ETH Züric*Mercè Teixidó, *Universitat de Lleida*Tomàs Pallejà, *Universitat de Lleida*

Cedric Pradalier, *ETH Züric* Jordi Roca, *Universitat de Lleida*

Design of communication and video system for a multi-legged subsea robot

Banghyun Kim, MOERI-KORDI Bong-Huan Jun, MOERI-KORDI Pan-Mook Lee, MOERI-KORDI Sung-Woo Park, MOERI-KORDI

Huxley: A flexible robot control architecture for autonomous underwater vehicles

Dani Goldberg, Bluefin Robotics Corporation

Approximated modeling of hydrodynamic forces acting on legs of underwater walking robot

Bong-Huan Jun, *MOERI-KORDI* Pan-Mook Lee Lee, *MOERI-KORDI* Hyuk Baek, *MOERI-KORDI* Yong-Kon Lim, *MOERI-KORDI*

Design concept of tsukuyomi - a prototype of underwater glider for virtual mooring

Kenichi Asakawa, Japan Agency for Marine-Earth Science and Technology Masahiko Nakamura, Research Institute for Applied Mechanics, Kyushu University

Taiyo Kobayashi, *Japan Agency for Marine-Earth Science and Technology* Yoshitaka Watanabe, *Japan Agency for Marine-Earth Science and Technology* Tadahiro Hyakudome, *Japan Agency for Marine-Earth Science and Technology* Yuzuru Ito, *Ocean Engineering Research*, *Inc.*

Junichi Kojima, KDDI Research and Development Laboratories

Array Signal Processing, Array Design and Vector Sensor Processing

6-Room 5 (Bahía Hall)

Tuesday, June 7 (3:00PM - 4:30PM)

Co-Chairs: Paulo Santos, ISR - University of Algarve

Hock Siong Lim, Thales Solutions Asia Pte Ltd

Particle filtering with enhanced likelihood model for underwater acoustic source DOA tracking

Xionghu Zhong, Centre for multimedia and network technology Hari Vishnu, School of Computer Engineering

A. Premkumar, School of Computer Engineering

A. S. Madhukumar, School of Computer Engineering

Angle of arrival estimation based on Warped Delay-and-Sum (WDAS) beamforming technique

Ali Massoud, *Queen's university, Kingston, Ontario* Aboelmagd Noureldin, *Royal Military College*

Underwater signal detection in partially known ocean using short acoustic vector sensor array

Hari Vishnu, *Nanyang Technological University* G. Anand, *Indian Institute Of Science, Bangalore* Annamalai Premkumar, *Nanyang Technological University* A. Madhukumar, *Nanyang Technological University*

Underwater acoustic positioning in dense multipath channels using a 2-Dwideband sparse array

Sung-Hoon Byun, MOERI/KORDI

Sea-Moon Kim, MOERI/KORDI

Pan-Mook Lee, MOERI/KORDI

Yong-Kon Lim, MOERI/KORDI

Woojae Seong, Seoul National University

Estimation and compensation of rotation perturbation in linear 2D Acoustic vector sensor array

Hock Siong Lim, *Thales Solutions Asia Pte Ltd* Ketan Rameshchandra, *Thales Solutions Asia Pte Ltd* Wei Siong Toh, *DSO National Laboratories*

Geometric and seabed parameter estimation using a vector sensor array - experimental results from makai experiment 2005

Paulo Santos, ISR - University of Algarve José João, ISE - University of Algarve Orlando Rodríguez, ISR - University of Algarve Paulo Felisberto, ISR - University of Algarve Sergio Jesús, ISR - University of Algarve

Marine Renewable Energy - 3

1-Assembly Room

Tuesday, June 7 (5:00PM - 6:30PM)

Chair: Y. Meriah Arias-Thode, SPAWAR Pacific

Viability of complementary sun concentrated based power plants for offshore structures

Ramon Garcia, *University of A Coruna* Manuel Casado, *University of Cadiz*

Stream analytical processing of acoustic signals for cetacean studies and environmental monitoring of ocean energy conversion devices

Harry Kolar, IBM Corporation

Eoin Sweeney, Sustainable Energy Authority or Ireland

Adam Russell, _

Eugene McKeown, Biospheric Engineering Ltd

Paul Gaughan, Marine Institute of Ireland

Aidan McGowan, IBM Corporation

Eric Bouillet, IBM Corporation

Development of microbial fuel cell prototypes for examination of the temporal and spatial response of anodic bacterial communities in marine sediments

Y. Meriah Arias-Thode, SPAWAR Pacific

Ken Richter, SPAWAR Pacific

Adriane Wotawa-Bergen, SPAWAR Pacific

D. Bart Chadwick, SPAWAR Pacific

Jinjun Kan, Stroud Water Research Center

Kenneth Nealson, University of Southern California

The high efficiency multi-less (HEML) fuel cell - a high energy power source for underwater vehicles, buoys, and stations

Hiroshi Yoshida, JAMSTEC

Tadahiro Hyakudome, JAMSTEC

Toshihiro Tani, Mitsubishi Heavy Industries, Ltd.

Shojiro Ishibashi, JAMSTEC

Mitsuyoshi Iwata, Mitsubishi Heavy Industries, Ltd.

Takuya Moriga, Mitsubishi Heavy Industries, Ltd.

Buoy Technology and Cables and Connectors

2-Room 1 (Bahía Hall)

Tuesday, June 7 (5:00PM - 6:30PM)

Co-Chairs: Enrique Peña, Water and Environmental Engineering Group (GEAMA).

University of A Coruña

Xulio Fernández-Hermida, University of Vigo

A low cost reconfigurable sensor network for coastal monitoring

Carlos De Marziani, National University of Patagonia San Juan Bosco/CONICET

Romulo Alcoleas, National University of Patagonia San Juan Bosco

Francisco Colombo, National University of Patagonia San Juan Bosco

Nicolás Costa, National University of Patagonia San Juan Bosco

Francisco Pujana, National University of Patagonia San Juan Bosco

Alejandro Colombo, National University of Patagonia San Juan Bosco

Joaquín Aparicio, University of Alcalá

Fernando Álvarez, University of Extremadura

Ana Jiménez, University of Alcalá

Jesús Ureña, University of Alcalá

Alvaro Hernández, University of Alcalá

Design and performance of a low power moored data buoy system

Srinivasan R

Shijo Zacharia

Thamarai T

Tata Sudhakar

M.Aravindakshan Atmanand

Strain gauges measurements of mooring lines and module connector forces in a physical model of the Aquete Port floating breakwater.

Enrique Peña, Water and Environmental Engineering Group (GEAMA).

University of A Coruña

Antia López, Water and Environmental Engineering Group (GEAMA).

University of A Coruña.

Javier Ferreras, Water and Environmental Engineering Group (GEAMA).

University of A Coruña.

Félix Sánchez-Tembleque, CITEEC (R+D Centre of Technological Innovation in Building an Civil Engineering), University of A Coruña.

Fernando López, Aquática Ingenieria Civil

Javier Sopelana, Aquática Ingeniería Civil

From research to commercial operations: The next generation Easy-to-Deploy (ETD) tsunami assessment buoy

Robert Lawson, Science Applications International Corporation

Christian Meinig, NOAA

David Graham, Science Applications International Corporation

Scott Stalin, NOAA

Dirk Tagawa, NOAA

N. Lawrence-Slavas, NOAA

Ross Hibbins, Australia Bureau of Meteorology

Brian Ingham, Australia Bureau of Meteorology

Hidroboya: an autonomus buoy for real time high quality sea and continental water data retrieval

Xulio Fernández-Hermida, University of Vigo

Carlos Durán-Neira, Centro de Investigaciones Submarinas (CIS).

Manuel Lago-Reguera, Centro de Investigaciones Submarinas (CIS).

Carlos Rodríguez-Alemparte, University of Vigo

Fernando Martín-Rodríguez, University of Vigo

Preliminary study of moored power cables

Joana Prat, UPC

Joaquin del Río Fernández, UPC - SARTI

Alejandro Arbos, UPC - SARTI

Hydrography

3-Room 2A (Bahía Hall)

Tuesday, June 7 (5:00PM - 6:30PM)

Co-Chairs: Ahmed El-Rabbany, Ryerson University

Dr. Genndii Kaloshin

SAS multipass interferometry for monitoring seabed deformation using a high-frequency imaging sonar

Claudio Prati, DEI - Politecnico di Milano

Riccardo De Paulis, Politecnico di Milano

Silvia Scirpoli, DEI - Politecnico di Milano

Fabio Rocca, DEI - Politecnico di Milano

Alessandra Tesei, NURC - Nato Undersea Research Centre

Per Arne Sletner, NURC - Nato Undersea Research Centre

Stefano Biagini, NURC - Nato Undersea Research Centre

Piero Guerrini, NURC - Nato Undersea Research Centre

Francesco Gasparoni, Tecnomare

Cosmo Carmisciano, *INGV* Marina Locritani, *INGV*

Development of visual laser lights for providing more effective coastal navigation

Genndii Kaloshin, V.E. Zuev Institute of Atmospheric Optics of Siberian Branch Russian Academy of Sciences

Program complex Range for the analysis and designing of visual aids to navigation of the seas

Genndii Kaloshin, V.E. Zuev Institute of Atmospheric Optics of Siberian Branch Russian Academy of Sciences

Sergei Shishkin, V.E. Zuev Institute of Atmospheric Optics of Siberian Branch Russian Academy of Sciences

GPS outage recovery using wavelet and neural network models in support of multibeam hydrography

Ahmed El-Rabbany, Ryerson University
Ashraf El-Assal, Arab Academy for Science and Technology
Saad Mesbah, Arab Academy for Science and Technology

Underwater Acoustics & Acoustical Oceanography

4-Room 3B (Bahía Hall)

Tuesday, June 7 (5:00PM - 6:30PM)

Co-Chairs: Alain Maguer, NATO Undersea Research Centre

Sergio Jesús, University of Algarve

NURC within glider sensors calibration, validation and monitoring facilities

Marina Ampolo Rella, NATO Undersea Research Centre Alain Maguer, NATO Undersea Research Centre Richard Stoner, NATO Undersea Research Centre Domenico Galletti, NATO Undersea Research Centre Eugenio Molinari, NATO Undersea Research Centre

HYDRA: High Yield Data Recording acoustic Array

Alain Maguer, NATO Undersea Research Centre Luigi Troiano, NATO Undersea Research Centre Rodney Dymond, NATO Undersea Research Centre Piero Guerrini, NATO Undersea Research Centre Alberto Dassatti, NATO Undersea Research Centre

Improving a novel image-processing based method for automatic detection, extraction and characterization of marine mammal tonal calls by means of a segmentation process based on learning machines

Rosa María Menchón Lara, *Universidad Politécnica de Cartagena* Antonio Sánchez García, *SAES*

Consuelo Bastida Jumilla, *Universidad Politécnica de Cartagena*Jorge Larrey Ruiz, *Universidad Politécnica de Cartagena*Rafael Verdú Monedero, *Universidad Politécnica de Cartagena*Juan Morales Sánchez, *Universidad Politécnica de Cartagena*José Luis Sancho-Gómez, *Universidad Politécnica de Cartagena*

Opportunistic XOR network coding for multihop data delivery in Underwater acoustic networks

Haojie Zhuang, Institute for Infocomm Research, A*STAR, Singapore Alvin Valera, Institute for Infocomm Research, A*STAR, Singapore Zhi Ang Eu, Institute for Infocomm Research, A*STAR, Singapore Pius Wei Qi Lee, Institute for Infocomm Research, A*STAR, Singapore Hwee-Pink Tan, Ilnstitute for Infocomm Research, A*STAR, Singapore

An integrated observation system with multiple acoustic arrays for underwater behavioral study of the Ganges river dolphins

Junichi Kojima, KDDI R&D Laboratories Inc.
Harumi Sugimatsu, The University of Tokyo
Tamaki Ura, The University of Tokyo
Rajendar Bahl, Indian Institute of Technology Delhi, India
Sandeep Behera, WWF-India
Vivek Sagar, WWF-India

Acoustic observatories for ocean tomography: multi-array matched-field tomography

Cristiano Soares, *Instituto de Sistemas e Robótica* Paulo Felisberto, *Instituto de Sistemas e Robótica* Sérgio Jesus, *Instituto de Sistemas e Robótica*

Vehicle Performance

5-Room 4B (Bahía Hall)

Tuesday, June 7 (5:00PM - 6:30PM)

Co-Chairs: Victor Lobo, CINAV-PO Navy Research Center/ISEGI-UNL

Haro M, University of Cádiz

Experiments of flipper type crawler system at sea to verify running performance on sandy or irregular steep terrain seafloor

. Tomoya Inoue, *JAMSTEC* Ken Takagi, *The University of Tokyo* Takuya Shiosawa, *The University of Tokyo*

Hydrodynamic investigation of the AUV PICASSO

Tomoya Inoue, JAMSTEC
Hiroyoshi Suzuki, Osaka University
Atsushi Yamamichi, Osaka University
Risa Kitamoto, Osaka University
Yoshitaka Watanabe, JAMSTEC
Hiroshi Yoshida. JAMSTEC

Ship's roll stabilization by anti-roll active tanks

Haro M, *University of Cádiz* Ferreiro Ramón, *University La Coruña* Francisco J Velasco, *University of Cantabria*

Real-time decision support system for monitoring stability and operational parameters of ships

Victor Lobo, CINAV-PO Navy Research Center/ISEGI-UNL Paulo Martins, CINAV-PO Navy Research Center

Mobility and agility of multi-legged subsea robot considering tidal current

Hyungwon Shim, Ocean Engineering Research Department/MOERI-KORDI Bong-Huan Jun, Ocean Engineering Research Department/MOERI-KORDI Yong-Kon Lim, Ocean Engineering Research Department/MOERI-KORDI Yong-Kon Lim, Ocean Engineering Research Department/MOERI-KORDI

Model-Based Signal Processing Techniques

6-Room 5 (Bahía Hall)

Tuesday, June 7 (5:00PM - 6:30PM)

Chair: James Candy, Lawrence Livermore National Laboratory

Adaptive particle filtering an approach to tracking modes in a varying shallow ocean environment

James Candy, Lawrence Livermore National Laboratory

Global extremum searching algorithm for the AUV guidance toward an acoustic buoy

Fedor Bezruchko, *Institute of Marine Technology Problems FEB RAS* Igor Burdinsky, *Pacific National University* Anton Myagotin, *St. Petersburg State University of Civil Aviation*

Raypath separation with high resolution processing

Long Jiang, GIPSA-Lab/DIS, Grenoble INP Florian Aulanier, Gipsa-lab/DIS Grenoble INP Grégoire Touzé, Gipsa-lab/DIS Grenoble INP Barbara Nicolas, Gipsa-lab/DIS Grenoble INP Jérôme Mars, Gipsa-lab/DIS Grenoble INP

Acoustic field calibration for noise prediction: the CALCOM'10 data set

Nélson Martins, *Universidade do Algarve* Paulo Felisberto, *Universidade do Algarve* Sérgio Jesus, *Universidade do Algarve*

Alternative approach of constructing a digital underwater communication system with negative SNR as well as higher security

Abolfazl Falahati, *Iran University of Science and Technology* Milad Johnny, *IUST*

Underwater channel modeling for a relative positioning system

Joaquín Aparicio Sosa, *University of Alcalá*Fernando Álvarez Franco, *University of Extremadura*Ana Jiménez Martín, *University of Alcalá*Carlos De Marziani, *Universidad Nacional de la Patagonia San Juan Bosco*Jesús Ureña Ureña, *University of Alcalá*Cristina Diego Guijarro, *University of Alcalá*

TECHNICAL PROGRAM

Wednesday, June 8

Marine Renewable Energy - 4

1-Assembly Room

Wednesday, June 8 (9:00AM - 11:00AM)

Co-Chairs: Edin Omerdic, University of Limerick

Pedro Díaz Simal, Universidad de Cantabria

New ICT cutting edge solutions for marine conditions prediction and logistics processes management in offshore renewable energy infrastructures installation and maintenance

Juan Gonzalez, Conceptual KLT

Pablo Castro, Conceptual KLT

Celestino Güemes. Mundivia

Raul Guanche, IH Cantabria, Universidad de Cantabria

Roberto Minguez ,IH Cantabria, Universidad de Cantabria

Design & development of assistive tools for future applications in the field of renewable ocean energy

Edin Omerdic, *University of Limerick* Daniel Toal, *University of Limerick* Sean Nolan, *University of Limerick* Hammad Ahmad, *University of Limerick*

Garret Duffy, NUIGalway

A marine test site for ocean energy converters: Oceanic Platform of the Canary Islands

Javier González, Oceanic platform of the Canary Islands (PLOCAN)
Vidina Monagas, Oceanic platform of the Canary Islands (PLOCAN)
Eric Delory, Oceanic Platform of the Canary Islands (PLOCAN)
Joaquín Hernández-Brito, Oceanic platform of the Canary Islands (PLOCAN)
Octavio Llinás, Oceanic platform of the Canary Islands (PLOCAN)

On the profitability of renewable energy facilities, what if equipment last less than expected?.

Pedro Díaz Simal, *Universidad de Cantabria* Saul Torres Ortega, *Universidad de Cantabria*

Building a roadmap for the implementation of marine renewable energy in Colombia

Andres Osorio, *Universidad Nacional de Colombia - Sede Medellín*Pablo Agudelo-Restrepo, *I Consult S.A.*Julio Correa, *Universidad Pontificia Bolivariana*Luis Otero, *Centro de Investigaciones Oceanográficas e Hidrográficas - C I O H*Santiago Ortega, *Universidad Nacional de Colombia - Sede Medellín*Jose Hernandez, *Empresas Publicas de Medellín*

A Multilateral Technology Initiative on Ocean Energy

Juan Restrepo, Empresas Publicas de Medellín

José Villate, *Tecnalia* John Huckerby, *AWATEA* Eoin Sweeney, *Sustainable Energy Authority of Ireland* Ana Brito-Melo, *Wave Energy Centre*

Ocean Dynamics: Wind, Waves, Surge and Sea Level

2-Room 1 (Bahía Hall)

Wednesday, June 8 (9:00AM - 11:00AM)

Chair: Fernando Méndez, Universidad de Cantabria

Oceano-meteorological conditions observed during severe storms in the southern Bay of Biscay

Daniel Cano, Instituto Español de Oceanografía (IEO)
Jose Luis Arteche, Agencia Estatal de Meteorología (AEMET)
Alicia Lavín, Instituto Español de Oceanografía (IEO)
Carmen Rodríguez, Instituto Español de Oceanografía (IEO)
Raquel Somavilla, Instituto Español de Oceanografía (IEO)
María Jesús García, Instituto Español de Oceanografía (IEO)

A methodology to define extreme wave climate using reanalysis data bases

Fernando Méndez, IH Cantabria, Universidad de Cantabria Antonio Tomas, IH Cantabria, Universidad de Cantabria Roberto Minguez, IH Cantabria, Universidad de Cantabria Borja Reguero, IH Cantabria, Universidad de Cantabria

The AGL buoy. A high frequency view of processes at the air-sea interface

Raquel Somavilla Cabrillo, Spanish Institute of Oceanography Alicia Lavin, Spanish Institute of Oceanography Carmen Rodriquez, Spanish Institute of Oceanography

Non parametric estimation of the sea state bias in Jason-1 measurements and their effect on Mediterranean mean sea surface height

Rami Ali, Centre of space techniques
Kahlouche salem, Centre of space techniques
Haddad mahdi, Centre of space techniques
Daniel Cano, Spanish Institute of Oceanography

Ocean Data, Modeling and Information Management

3-Room 2A (Bahía Hall)

Wednesday, June 8 (9:00AM - 11:00AM)

Chair: Enrique Coiras, European Union Satellite Centre

DAMAR: Information management system for marine data

Antonia Casas, Instituto Español de Oceanografía María Jesús García, Instituto Español de Oceanografía Andrei Nikouline, Instituto Español de Oceanografía

Mosaicking Synthetic Aperture Sonar Images using Dynamic Constraints

Enrique Coiras, European Union Satellite Centre David Williams, NATO Undersea Research Centre Johannes Groen, NATO Undersea Research Centre

Answering environmental european directives through information systems

Felipe Fernández, IH Cantabria, Universidad de Cantabria Víctor Velarde, IH Cantabria, Universidad de Cantabria Araceli Puente, IH Cantabria, Universidad de Cantabria Jose Antonio Juanes, IH Cantabria, Universidad de Cantabria Raúl Medina, IH Cantabria, Universidad de Cantabria

Simulation benchmark for autonomous marine vehicles in Labview

Alejandro Moreno, UNED David Moreno, UNED Dictino Chaos, UNED Joaquín Almansa, UNED

Application of multivariate modeling and analysis on an integrated hydrocarbon sensor array system for marine surveys

Xiubin Qi, CSIRO Emma Crooke, CSIRO Andrew Ross, CSIRO

The prediction of calm opportunities for landing on a ship

Juan Jesus Hernández, *Ministerio de Defensa* Jose Maria Rodríguez, *Ministerio de Defensa* Jose Maria Sierra, *Universidad Complutense de Madrid*

Optics, Imaging, Vision and E-M Systems

4-Room 3B (Bahía Hall)

Wednesday, June 8 (9:00AM - 11:00AM)

Co-Chairs: Jules Jaffe, *Marine Physical Lab*Anne-Gaëlle Allais. *IFREMER*

Challenges of close-range underwater optical mapping

Ricard Prados, *Universitat de Girona* Rafael Garcia, *Universitat de Girona* Javier Escartín, *CNRS UMR 7154* László Neumann, *ICREA*

Omni-Cam: An autonomous free-decent omni-directional camera for measuring radiance in marine environments.

Jules Jaffe, *Marine Physical Lab* Fernando Simonet, *Marine Physical Lab* Ben Laxton, *Marine Physical Lab*

Aerosol model development for environmental monitoring in the coastal atmosphere surface layer

Genndii Kaloshin, V.E. Zuev Institute of Atmospheric Optics of Siberian Branch Russian Academy of Sciences

A multi-modal event detection system for river and coastal marine monitoring applications

Edel O'Connor, *MESTECH* Alan Smeaton, CLARITY Noel O'Connor, *CLARITY*

Feature extraction for underwater visual SLAM

Josep Aulinas, Institute of Informatics and Applications
Marc Carreras, Institute of Informatics and Applications
Xavier Lladó, Institute of Informatics and Applications
Joaquim Salvi, Institute of Informatics and Applications
Wan Petillot, Ocean Systems Lab/School of EPS
Rafael Garcia, Institute of Informatics and Applications
Ricard Prados, Institute of Informatics and Applications

SOFI: a 3D simulator for the generation of underwater optical images

Anne-Gaëlle Allais, IFREMER

Matthieu Boffety, Institut Fresnel, CNRS, Aix-Marseille Université,Ecole Centrale Marseille

Marie-Edith Bouhier, IFREMER

Malik Chami, Observatoire Oceanologique de Villefranche, Laboratoire d'Oceanographie de Villefranche, Universite Pierre et Marie Curie, CNRS, Institut Universitaire de France

Kerstin Ebert, Observatoire Oceanologique de Villefranche, Laboratoire d'Oceanographie de Villefranche, CNRS

Toussaint Edmond, IFREMER

Frédéric Galland, Institut Fresnel, CNRS, Aix-Marseille Université, Ecole Centrale Marseille

Nicolas Maciol, *Société PROLEXIA* Stéphane Nicolas, *Société PROLEXIA*

Vehicle Navigation I

5-Room 4B (Bahía Hall)

Wednesday, June 8 (9:00AM - 11:00AM)

Chair: Francisco J. Velasco, University of Cantabria

Achieving high navigation accuracy using inertial navigation systems in autonomous underwater vehicles

Robert Panish, Bluefin Robotics Mikell Taylor, Bluefin Robotics

Path planning with homotopy class constraints on bathymetric maps

Emili Hernández, University of Girona Marc Carreras, University of Girona Enric Galceran, University of Girona Pere Ridao, University of Girona

Study on presentation of navigational information for support of safety of a ship by GIS

Shigeaki Shiotani, *Kobe University*Shinchiku Ryu, *Kobe University*Hidenari Makino, *Kobe University*Nobukazu Wakabayshi, *Kobe University*Yoichi Shimada, *Kobe University*

Multi-resolution path planning system for marine surface vehicle considering ocean environmental loads

TaeHwan Lee, *KAIST* Hyun Chung, *KAIST* Hyun Myung, *KAIST*

Single and multiple glider path planning using an optimization-based approach

Enrique Fernández-Perdomo, *Universidad de Las Palmas de Gran Canaria*Josep Isern-González, *Universidad de Las Palmas de Gran Canaria*Daniel Hernández-Sosa, *Universidad de Las Palmas de Gran Canaria*Jorge Cabrera-Gámez, *Universidad de Las Palmas de Gran Canaria*Antonio Domínguez-Brito, *Universidad de Las Palmas de Gran Canaria*Víctor Prieto-Marañón, *Universidad de Las Palmas de Gran Canaria*

The underwater GPS problem

Gunnar Taraldsen, SINTEF Information and Communication Technology
Tor Arne Reinen, SINTEF Information and Communication Technology
Tone Berg, SINTEF Information and Communication Technology

Sonar imaging, Syntetic Aperture, Classification and Pattern Recognition I

6-Room 5 (Bahía Hall)

Wednesday, June 8 (9:00AM - 11:00AM)

Co-Chairs: Olga Lopera, Royal Military Academy

Marek Moszynski, Gdansk University of Technology

First ocean survey with synthetic aperture sonar on neutral trim tow-fish

Takao Sawa, *JAMSTEC*Takashi Kasaya, *JAMSTEC*Hiroshi Yakihara, *KAGOSHIMA Univ.*

3D reconstruction of underwater scenes using DIDSON acoustic sonar image sequences through evolutionary algorithms

Naouraz Brahim, *Université Laval, Télécom Bretagne* Didier Guériot, *Télécom Bretagne* Sylvie Daniel, *Université Laval*

A novel approach to the focussing evaluation of sonar images

Krzysztof Czarnecki, Gdansk University of Technology Marek Moszynski, Gdansk University of Technology Miroslaw Rojewski, Gdansk University of Technology

Sidescan sonar imagery processing software for underwater research

Jose Zamanillo, *University of Cantabria* Isabel Zamanillo, *University of Cantabria* Francisco Velasco, *University of Cantabria* Elias Revestido, *University of Cantabria*

Marine Renewable Energy - 5 MAREN

1-Assembly Room Wednesday, June 8 (11:30AM - 1:30PM) Chair: Mario Canteli, *University of Cantabria*

Modelling Wave Energy Resources for UK?s Southwest Coast

Ana Rute Bento, *Technical University of Lisbon* Paulo Martinho, *Technical University of Lisbon* Carlos Soares, *Technical University of Lisbon*

WET: A Wave Energy Toolbox for oscillating-body converters

Mario Canteli, University of Cantabria
Severiano Pérez Remesal, University of Cantabria
Inmaculada Fernández Diego, University of Cantabria
Fernando Delgado San Román, University of Cantabria
Victor Manuel Moreno Saiz, University of Cantabria
Alberto Pigazo López, University of Cantabria
Paloma Roa Tortosa, Iberdrola Renovables S.A.
Alberto Arroyo Gutiérrez, University of Cantabria
Jorge Cardenal, Iberdrola Renovables S.A.
Ahmed Zobaa, Brunel University
Delfin Silio, University of Cantabria

Downscaling wave energy resources to coastal areas

Paula Camus, IH Cantabria, Universidad de Cantabria Antonio Tomas, IH Cantabria, Universidad de Cantabria Cesar Vidal, IH Cantabria, Universidad de Cantabria Fernando J. Mendez, IH Cantabria, Universidad de Cantabria Raul Medina, IH Cantabria, Universidad de Cantabria Inigo J. Losada, IH Cantabria, Universidad de Cantabria

Directional calibrated wind and wave reanalysis databases using Instrumental data for optimal design of off-shore wind farms

Antonio Espejo, *IH Cantabria, Universidad de Cantabria* Roberto Minguez, *IH Cantabria, Universidad de Cantabria*

Melisa Menéndez *IH Cantabria, Universidad de Cantabria* Fernando Méndez, *IH Cantabria, Universidad de Cantabria* Iñigo Losada, *IH Cantabria, Universidad de Cantabria*

A methodology to evaluate regional-scale offshore wind energy resources.

Melisa Menendez, IH Cantabria, Universidad de Cantabria
Antonio Tomás, IH Cantabria, Universidad de Cantabria
Paula Camus, IH Cantabria, Universidad de Cantabria
Markel García-Díez, Santander Meteorology Group, Universidad de Cantabria
Jesus Fernández, Santander Meteorology Group, Universidad de Cantabria
Lluis Fita, Santander Meteorology Group, Universidad de Cantabria
Fernando Méndez, IH Cantabria, Universidad de Cantabria
Iñigo Losada, IH Cantabria, Universidad de Cantabria

Coastal Hydrodynamics

2-Room 1 (Bahía Hall) Wednesday, June 8 (11:30AM - 1:30PM) Chair: Igor Shugan, *National Cheng Kung University*

Field studies on the hydrodynamic behavior of brine discharges

Francisco Vila, CEDEX-CEPYC
Macarena Rodrigo, CEDEX-CEPYC
Antonio Ruiz-Mateo, CEDEX-CEPYC
Ana Alvarez, CEDEX-CEPYC
Ana Lloret, CEDEX-CEPYC
Manuel Antequera, CEDEX-CEPYC

A lagrangian transport model applied to two different brackish systems: the Baltic Sea and the Guadalquivir River

Manuel Toscano-Jiménez, *University of Seville* Jose María Abril, *University of Seville*

Surface waves excitation by internal wave

Igor Shugan, *National Cheng Kung University* Hwung - Hweng Hwung, *National Cheng Kung University* Ray-Yeng Yang, *National Cheng Kung University*

Oil spill trajectory forecasting and backtracking using surface currents from high-frecuency (HF) radar technology

Ana Abascal, IH Cantabria, Universidad de Cantabria Sonia Castanedo, IH Cantabria, Universidad de Cantabria Vicente Fernández, Qualitas Remos S.A. María Ferrer, Qualitas Remos S.A.

Raúl Medina, IH Cantabria, Universidad de Cantabria

MEDVSA: a methodology for the design of brine discharges into seawater. Brine discharge modeling

Pilar Palomar, IH Cantabria, Universidad de Cantabria Javier L. Lara, IH Cantabria, Universidad de Cantabria Iñigo Losada, IH Cantabria, Universidad de Cantabria Macarena Rodrigo, CEDEX

Coastal Engineering and Estuarine Systems

3-Room 2A (Bahía Hall)

Wednesday, June 8 (11:30AM - 1:30PM)

Co-Chairs: Eoghan Long, Hydraulics and Maritime Research Centre,

University College Cork

Michael O'Shea, University College Cork.

Monitoring the morphodynamic behaviour of a breached barrier beach Ssystem and its impacts on an estuarine system

Michael O'Shea, *UCC* Jimmy Murphy, *UCC* Patricia Sala, *UCC*

Innovative measures to mitigate overtopping of coastal structures

Eoghan Long, Hydraulics and Maritime Research Centre, University College Cork Jimmy Murphy, Hydraulics and Maritime Research Centre, University College Cork

New vertical floating barrier to protect against sea waves and ship waves

Sopelana Javier, Aquática Ingenieria Civil Lopez Fernando, *Aquática Ingenieria Civil*

Rocha M Jesus, AISTER

Lomonaco Pedro, IH Cantabria, Universidad de Cantabria

Peña Enrique, GEAMA

Sanchez Felix, CITTEC

Rodriguez Juan Antonio, Portos de Galicia

Urquijo Pedro, Portos de Galicia

Measurements of bed level oscillation cycles in the surf zone of Sandy Beach

Gael Arnaud, SIAME/LaSAGeC Mathieu Mory, SIAME/LaSAGeC Denis Morichon, SIAME/LaSAGeC Stéphane Abadie, SIAME/LaSAGeC

Failure probability of marine steel sheet pile structures with special consideration of the corrosion impact

Paulo Osório, *University of Luxembourg*Christoph Odenbreit, *University of Luxembourg*Stefan Van Baars, *University of Luxembourg*Ton Vrouwenvelder, *Delft Institute of Technology*

Optical Sensors, Marine Optics Technology and Instrumentation

4-Room 3B (Bahía Hall)

Wednesday, June 8 (11:30AM - 1:30PM)

Chair: Davide Brizzolara, University of Genoa

In situ raman probe for quantitative observation of marine sediment pore water geochemistry in the deep ocean

Xin Zhang, Key Lab of Marine Geology and Environment, Institute of Oceanology, Chinese Academy of Sciences

William Kirkwood, Monterey Bay Aquarium Res. Inst.

Keith Hester, Conoco Phillips

Peter Walz, Monterey Bay Aquarium Res. Inst.

William Ussler, Monterey Bay Aquarium Res. Inst.

Edward Peltzer, Monterey Bay Aquarium Res. Inst.

Peter Brewer, Monterey Bay Aquarium Res. Inst.

Farley Shane, MBARI

The study of the underwater camera model

Sojiro Ishibashi, JAMSTEC

The sub sea holodeck: a 14-megapixel immersive virtual environment for studying cephalopod camouflage behavior

Jules Jaffe, *Marine Physical Lab* Ben Laxton, *Marine Physical Lab* Sarah Zylinski, *Duke University*

A vision-based system for on-board identification and estimation of discarded biomass: a tool for contributing to marine resources sustainability

Luis Antelo, *Instituto de Investigaciones Marinas - CSIC* Tatiana Ordoñez, *Instituto de Investigaciones Marinas - CSIC* Iñaki Miniño, *Marexi Marine Technology Co*.

Joaquín Gracia, Marexi Marine Technology Co.

Emilio Ribes, Instituto Tecnológico de Óptica, Color e Imagen - AIDO Juan Hervas, Instituto Tecnológico de Óptica, Color e Imagen - AIDO Santiago Simón, Instituto Tecnológico de Óptica, Color e Imagen - AIDO Antonio Alonso, Instituto de Investigaciones Marinas - CSIC

Optical wireless underwater communication for AUVs: Preliminary simulations and experimental results

Davide Brizzolara, University of Genoa Davide Anguita, University of Genoa Giancarlo Parodi, University of Genoa Qilong Hu, University of Genoa

Detection of Interest Points in Turbid Underwater Images

Rafael García, *Universitat de Girona* Nuno Gracias, *Universitat de Girona*

Vehicle Navigation II

5-Room 4B (Bahía Hall)

Wednesday, June 8 (11:30AM - 1:30PM)

Co-Chairs: Francisco J. Velasco, *Universidad de Cantabria*

Daniel Hernández-Sosa, Universidad de Las Palmas de Gran Canaria

A biologically inspired neural network for navigation with obstacle Avoidance in autonomous underwater and surface vehicles

Antonio González, *Universidad Politécnica de Cartagena* Francisco Cordova, *Universidad Politécnica de Cartagena* Javier Cervera, *Universidad Politécnica de Cartagena*

Ship maneuvering planning using swarm intelligence

Jose Escario, *Universidad Complutense de Madrid* Juan Castellanos, *Universidad Complutense de Madrid*

Deep-sea seafloor shape reconstruction from side-scan sonar data for AUV navigation

Philipp Woock, Fraunhofer Institute of Optronics, System Technologies and Image Exploitation IOSB

Autonomous mine hunting mission for the Charlie USV

Gabriele Bruzzone, *CNR - ISSIA* Giorgio Bruzzone, *CNR - ISSIA* Marco Bibuli, *CNR - ISSIA* Massimo Caccia, *CNR - ISSIA*

SLAM with adaptive noise tuning for the marine environment

Akshay Rao, *Nanyang Technological University*John Mullane, *Nanyang Technological University*Wijerupage Wijesoma, *Nanyang Technological University*Nicholas Patrikalakis, *Massachusetts Institute of Technology*

Long Baseline Beacon Position Estimation

Marcelo Nogueira, Faculdade de Engenharia da Universidade do Porto

Acoustic Telemetry and Communication I

6-Room 5 (Bahía Hall) Wednesday, June 8 (11:30AM - 1:30PM) Chair: Antonio Silva, *University of Algarve*

An energy-efficient routing protocol for UWSNs using physical distance and residual energy

Wahid, *Kyungpook National University* Sungwon Lee, *MONET* DongKyun Kim, *MONET*

Adaptive frequency-domain equalization for underwater acoustic communications

Abdelhakim Yuocef, *Telecom Bretagne* Christophe Laot, *Telecom Bretagne* Karine Amis Cavalec, *Telecom Bretagne*

Mobile multi-input multi-output underwater acoustic communications

Kexin Zhao, *University of Florida* Jun Ling, *University of Florida* Jian Li, *University of Florida*

Characterization of underwater acoustic channel using slowly moving transmitter in shallow water

Sea-Moon Kim, MOERI/KORDI Sung-Hoon Byun, MOERI/KORDI Seung-Geun Kim, MOERI/KORDI Yong-Kon Lim, MOERI/KORDI

Statistical characteristics of digital hydro-acoustic signal with Sweep-spread carrier in the receiver predetection point

Konstantin Kebkal, EvoLogics GmbH Rudolf Bannasch, EvoLogics GmbH Oleksiy Kebkal, EvoLogics GmbH

D-MAC: Media access control architecture for underwater acoustic sensor networks

Oleksiy Kebkal, EvoLogics GmbH Maxim Komar, EvoLogics GmbH Konstantin Kebkal, EvoLogics GmbH Rudolf Bannasch, EvoLogics GmbH

Sonar Imaging, Synthetic Aperture, Classificarion and Pattern Recognition II

7-Room 3A (Bahía Hall) Wednesday, June 8 (11:30AM - 1:30PM)

Chair: Jose M. Zamanillo, Universidad de Cantabria

A fast physics-based, environmentally adaptive underwater object detection algorithm

David Williams, NATO Undersea Research Centre Johannes Groen, NATO Undersea Research Centre

Combining despeckling and segmentation techniques to facilitate detection and identification of seafloor targets

Olga Lopera, *Royal Military Academy* Wes Dupont, *Ministry of Defense*

Quality assessment of synthetic aperture sonar images based on a single ping reference

Stefan Leier, Technische Universität Darmstadt Abdelhak Zoubir, Technische Universität Darmstadt

Marine Renewable Energy - 6

1-Assembly Room

Wednesday, June 8 (3:00PM - 4:30PM)

Co-Chairs: Hassan Mahfuz Mahfuz, Florida Atlantic University

Andres Osorio, Universidad Nacional de Colombia - Sede Medellín

Life prediction of composite turbine blades under random ocean current and velocity shear

Hassan Mahfuz Mahfuz, Florida Atlantic University Mohammad Akram, University of Illinois at Urbana Champaign

Assessing the impact of ADCP resolution and sampling rate on tidal current energy project economics

Tim Stiven, *Ocean Power Technologies Ltd.*Scott Couch, *University of Edinburgh*Abhinaya Iyer, *University of Edinburgh*

Dynamic behavior of a second generation hydrokinetic converter

Amable López Piñeiro, *Universidad Politécnica de Madrid* José Andrés Somolinos, *Universidad Politécnica de Madrid* Luis Ramón Núñez Rivas, *Universidad Politécnica de Madrid* Jesús Valle Cabezas, *Universidad Politécnica de Madrid*

European Projects on Underwater Networks - 1

2-Room 1 (Bahía Hall)

Wednesday, June 8 (3:00PM - 4:30PM)

Chair: Henry Dol, TNO

AUVs as mobile nodes in acoustic communication networks: field experience at the UAN10 experiment

Andrea Caiti, *University of Pisa*Vincenzo Calabro, *University of Pisa*Gianluca Dini, *University of Pisa*Angelica Lo Duca, *University of Pisa*Andrea Munafo', *University of Pisa*

A comperative view of routing protocols for underwater sensor networks

Yonca Bayrakdar, *Ege University* Nirvana Meratnia, *Twente University Pervasive Systems Group* Aylin Kantarci, *Ege University*

RACUN (Robust Acoustic Communications in Underwater Networks): An Overview

Jörg Kalwa, ATLAS ELEKTRONIK GmbH

Underwater sensing and communication platform

Kui Zhang, University of Twente, Pervasive Systems
Wouter van Kleunen, University of Twente, Pervasive Systems
Paul Havinga, University of Twente, Pervasive Systems
Nirvana Meratnia, University of Twente, Pervasive Systems
Emiel Tijs, Microflown Technologies

Implementation of an underwater acoustic modem with network capability

Thor Husoy, Kongsberg Maritime
Magne Pettersen, Kongsberg Maritime
Bernt Nilsson, FOI Swedish Defence Research Agency
Tommy Öberg, FOI Swedish Defence Research Agency
Narada Warakagoda, Sintef ICT
Arne Lie, Sintef ICT

Oceanography: Physical, Chemical and Biological

3-Room 2A (Bahía Hall)

Wednesday, June 8 (3:00PM - 4:30PM)

Co-Chairs: Daniel Hayes, Oceanography Center, University of Cyprus

Giorgio Caramanna, The University of Nottingham

Preliminary results of project MAST/AM: advanced tracking and telemetry methodologies to study marine animals

Paulo Oliveira, ISR-501507930

Carlos Silvestre. IST/ISR

Marco Morgado, IST/ISR

Karim Erzini, Universidade do Algarve

Luis Bentes, Universidade do Algarve

André Afonso, Universidade do Algarve

Fábio Hazin, Universidade Federal Rural de Pernambuco

Barbara Block, Stanford University

Glider transects in the Levantine Sea: characteristics of the warm core Cyprus Eddy

Daniel Hayes, Oceanography Center, University of Cyprus Pierre Testor, LOCEAN-IPSL/CNRS, Universite Pierre et Marie Curie George Zodiatis, Oceanography Center, University of Cyprus

Gregory Konnaris, Oceanography Center, University of Cyprus Angelos Hannides, Oceanography Center, University of Cyprus Dmitry Solovyov, Oceanography Center, University of Cyprus

Eight years of research on a marine natural analogue for sub-seabed CO2 storage seepage

Giorgio Caramanna, *The University of Nottingham* Nunzia Voltattorni, *Istituto Nazionale di Geofisica e Vulcanologia* Mercedes Maroto-Valer, *The University of Nottingham*

Variability of phytoplankton communities in central east atlantic (ESTOC)

Daura Vega Moreno, Instituto Canario de Ciencias Marinas Carolina Llerandi, Instituto Canario de Ciencias Marinas Andrés Cianca, Instituto Canario de Ciencias Marinas Laura Cardona, Instituto Canario de Ciencias Marinas Marimar Villagarcía, Instituto Canario de Ciencias Marinas Rosa Santana, Instituto Canario de Ciencias Marinas María José Rueda, Instituto Canario de Ciencias Marinas Octavio Llinás, Plataforma Oceánica de Canarias

Compact archival tags for the migratory studies of marine species

Prajas John, Cochin University of Science and Technology Adrine Correya, Cochin University of Science and Technology Supriya H, Cochin University of Science and Technology P. R. Pillai, Cochin University of Science and Technology

3D Imaging and Holography

4-Room 3B (Bahía Hall) Wednesday, June 8 (3:00PM - 4:30PM)

Chair: Luis Antelo, Instituto de Investigaciones Marinas - CSIC

First sea trials of a laser aided three dimensional underwater image mosaicing technique

Lorenzo Brignone, IFREMER Matteo Munaro, IFREMER Anne-Gaëlle Allais, IFREMER Jan Opderbecke, IFREMER

Using in-situ holographic microscopy for ocean particle characterization

James Sullivan, WET Labs, Inc. Joseph Katz, Johns Hopkins University

Siddharth Talapatra, Johns Hopkins University Michael Twardowski, WET Labs, Inc. Jiarong Hong, Johns Hopkins University Percy Donaghay, University of Rhode Island

Bundle adjustment in large-scale 3D reconstructions based on underwater robotic surveys

Chris Beall, *Georgia Tech* Frank Dellaert, *Georgia Tech* Ian Mahon, *Australian Centre for Field Robotics* Stefan Williams, *Australian Centre for Field Robotics*

Surface reconstruction methods for the recovery of 3D models from underwater interest areas

Ricard Campos, *University of Girona* Rafael García, *University of Girona* Tudor Nicosevici, *University of Girona*

Evaluation the plankton particle coordinates from digital holographic video

Victor Dyomin, Tomsk State University Alexey Olshukov, Tomsk State University Denis Kamenev, Tomsk State University

Autonomous Underwater Vehicles I

5-Room 4B (Bahía Hall) Wednesday, June 8 (3:00PM - 4:30PM) Chair: Christian Degel, *Fraunhofer IBMT*

Automatic reconfiguration and control of the MARES AUV in the presence of a thruster fault

Bruno Ferreira, INESC Porto / University of Porto Anibal Matos, INESC Porto / University of Porto Nuno Cruz, INESC Porto / University of Porto

On the effects of node mobility on energy efficiency and delay sensitive applications in underwater sensor network

El Hadi Cherkaoui, Istituto Italiano di Tecnologia Laura Toni, Istituto Italiano di Tecnologia Lorenzo Rossi, Istituto Italiano di Tecnologia Jean-Guy Fontaine, Istituto Italiano di Tecnologia Nazim Aqoulmine, LRSM IBISC University of Evry Val d'Essonne

REP10 AUV: Shallow water operations with heterogeneous autonomous vehicles

Ricardo Martins, FEUP João Sousa, FEUP Carlos Afonso, Citan Portuguese Navy

Leader-follower control of underwater vehicles over acoustic communica-

Pedro Ribeiro, Faculdade de Engenharia da Universidade do Porto João Sousa, Faculdade de Engenharia da Universidade do Porto

Docking problem and guidance laws considering drift for an underactuated AUV

Jin-Yeong Park, Maritime & Ocean Engineering Research Institute / KORDI Bong-Huan Jun, Maritime & Ocean Engineering Research Institute / KORDI Pan-Mook Lee, Maritime & Ocean Engineering Research Institute / KORDI Jun-Ho Oh, Humanoid Robot Research Center/KAIST Yong-Kon Lim, Maritime & Ocean Engineering Research Institute / KORDI

Obstacle avoidance using echo sounder sonar

Pedro Ribeiro, Faculdade de Engenharia da Universidade do Porto Marcelo Nogueira, Faculdade de Engenharia da Universidade do Porto Ricardo Gomes, Faculdade de Engenharia da Universidade do Porto Ricardo Gomes, Faculdade de Engenharia da Universidade do Porto Joana Cardoso, Faculdade de Engenharia da Universidade do Porto Pedro Teixeira, Faculdade de Engenharia da Universidade do Porto Sujit B, Faculdade de Engenharia da Universidade do Porto João Sousa, Faculdade de Engenharia da Universidade do Porto

Acoustic Telemetry and Communication II

6-Room 5 (Bahía Hall)

Wednesday, June 8 (3:00PM - 4:30PM)

Co-Chairs: Roberto Petroccia, Università di Roma "La Sapienza"

Qinqing Zhang, Johns Hopkins University, Applied Physics Lab

DSSS: A TDMA-based MAC protocol with dynamic slot scheduling strategy for underwater acoustic sensor networks

Yen-Da Chen, Department of Computer Information and Network Engineering, Lunghwa University of Science and Technology

Chan-Ying Lien, Department of Computer Science and Information Engineering Tamkang University

Sun-Wei Chuang, Department of Computer Science and Information Engineering Tamkang University

Kuei-Ping Shih, Department of Computer Science and Information Engineering Tamkang University

Probe timing optimization for time-reversal underwater communications

Antonio Silva, *University of Algarve* Sergio Jesús, *University of Algarve* João Gomes, *Instituto Superior Técnico*

From underwater simulation to at-sea testing using the NS-2 network simulator

Roberto Petroccia, *Università di Roma "La Sapienza"* Chiara Petrioli, *Università di Roma "La Sapienza"* Lee Freitag, *Woods Hole Oceanographic Institution* Jon Shusta, *Woods Hole Oceanographic Institution*

Adaptive power control for underwater acoustic communications

Parastoo Qarabaqi, *Northeastern University* Milica Stojanovic, *Northeastern University*

Performance of hydro-acoustic data transmission in horizontal channels using sweep-spread signaling and turbocoding

Veronika Kebkal, EvoLogics GmbH Rudolf Bannasch, EvoLogics GmbH Konstantin Kebkal, EvoLogics GmbH

Marine Renewable Energy - 7

1-Assembly Room

Wednesday, June 8 (5:00PM - 6:30PM)

Co-Chairs: Reza Chini, Memorial University of Newfoundland

Amadou Thiam, Boston University

Blades optimization for an ocean current horizontal axis turbine using response surface methodology

Reza Chini, Memorial University of Newfoundland Martin Ordonez, Simon Fraser University Ralf Bachmayer, Memorial University of Newfoundland

Numerical simulation of a submerged wave energy converter under irregular wave conditions

Victoria Gómez, IH Cantabria, Universidad de Cantabria Raúl Guanche, IH Cantabria, Universidad de Cantabria Cesar Vidal, IH Cantabria, Universidad de Cantabria Irene Eguinoa, MTorres

Upper limits to the power that can be extracted from ocean waves by Pelamis-type energy devices

Amadou Thiam, Boston University Allan Pierce, Boston University

European Projects on Underwater Networks - 2

2-Room 1 (Bahía Hall)

Wednesday, June 8 (5:00PM - 6:30PM)

Co-Chairs: Gianluca Antonelli, ISME - University of Cassino

Andrea CAITI, Dep. of Energy and Systems Engineering

Underwater acoustic communication research at TNO - past and present

Henry Dol, *TNO* Paul van Walree, *FFI*

UAN - Underwater Acoustic Network

Sergio Jesús, University of Algarve
Andrea Caiti, ISME, Universita di Genova
Paulo Felisberto, Universidade do Algarve
Thor Husoy, Kongsberg Maritime
Ilkka Karasalo, FOI
Riccardo Massimelli, Selex Sistemi Integrati SPA
Tor Reinen, Stiftelsen Sintef
Antonio Silva, ISR - University of Algarve

The CO3AUVs (Cooperative Cognitive Control for Autonomous Underwater Vehicles) Project: overview and current progresses

Gianluca Antonelli, ISME - University of Cassino Andrea Caiti, ISME - University of Pisa Giuseppe Casalino, ISME - University of Genova Giovanni Indiveri, ISME - University of Salento Andreas Birk, Jacobs University Antonio Pascoal, Instituto Superior Tecnico Andrea Caffaz, Graal Tech

Underwater communications for moving source using geometry-adapted time reversal and DFE: UAN10 data

Usa Vilaipornsawai, *University of Algarv*e António Silva, *University of Algarve* Sérgio Jesús, *University of Algarve*

On the impact of the environment on MAC and routing in shallow water scenarios

Saiful Azad, University of Padova

Paolo Casari, Department of Information Engineering, University of Padova Chiara Petrioli, University of Rome, "La Sapienza"

Roberto Petroccia, Department of Computer Science, University of Rome
Michele Zorzi, Department of Information Engineering, University of Padova

Marine Law, Management and Safety

3-Room 2A (Bahía Hall)

Wednesday, June 8 (5:00PM - 6:30PM)

Chair: Carlos Perez-Labajos, University of Cantabria

Option and Quasyoption value: an approach to deal with climate change effects in coastal areas

Pedro Díaz Simal, *Universidad de Cantabria* Saul Torres Ortega, *Universidad de Cantabria*

Promoting an optimal networking of fishing actors to organize a responsible, optimal and sustainable exploitation of marine resources:

the FAROS Initiative

Luis Antelo, Instituto de Investigaciones Marinas - CSIC

Tatiana Ordoñez, Instituto de Investigaciones Marinas - CSIC

Amaya Franco-Uría, Instituto de Investigaciones Marinas - CSIC

José Luis Gómez-Gesteira, Centro Tecnológico del Mar - Fundación CETMAR

María Luisa Fernández-Cañamero, Centro Tecnológico del Mar - Fundación CE-TMAR

Nélida Pérez, Centro Oceanográfico de Vigo - Instituto Español de Oceanografía José Castro, Centro Oceanográfico de Vigo - Instituto Español de Oceanografía José María Bellido, Centro Oceanográfico de Murcia - Instituto Español de Oceanografía

Francisco Landeira, Centro de Supercomputación de Galicia - CESGA Antonio Alonso, Instituto de Investigaciones Marinas - CSIC

Flooding accidents in Spanish fishing boats

Carlos Perez-Labajos, *University of Cantabria*Beatriz Blanco, *University of Cantabria*Lidia Sánchez, *University of Cantabria*Rafael Rodríguez, *University of Cantabria*Andres R. Ortega, *University of Cantabria*

Oceanographic Instrumentation, Sensors and Current Measurement Technology I

4-Room 3B (Bahía Hall) Wednesday, June 8 (5:00PM - 6:30PM)

Chair: Albert Williams, Woods Hole Oceanographic Institution

Calibration process of geophones

Xavier Roset, *Polytechnic University of Catalonia*Albert Garcia, *Polytechnic University of Catalonia*Antoni Mànuel, *Polytechnic University of Catalonia*Julian González, *UPC*

Thirteen years of drifting data. Surface currents in the Canary region

Laura Cardona, Canary Institute of Marine Science (ICCM)
Marimar Villagarcía, Canary Institute of Marine Science (ICCM)
Javier Pérez-Marrero, Canary Institute of Marine Science (ICCM)
Rosa Santana, University of Las Palmas de Gran Canaria
Andres Cianca, Canary Institute of Marine Sciences
Carlos Barrera, Oceanic Platform of the Canary Islands (PLOCAN)
Carolina García, Canary Institute of Marine Sciences
Daura Vega-Moreno, University of Las Palmas de Gran Canaria
Maria José Rueda, Canary Institute of Marine Sciences
Octavio Llinás, Oceanic Platform of the Canary Islands (PLOCAN)

Flux measurements from an ice tethered profiler: first look

Fredrik Thwaites, Woods Hole Oceanographic Institution Richard Krishfield, Woods Hole Oceanographic Institution Mary-Louise Timmermanns, Yale University John Toole, Woods Hole Oceanographic Institution Albert Williams, Woods Hole Oceanographic Institution

A system to monitoring marine environment based on wireless sensor network

Cristina Perez, Technical University of Cartagena Roque Sanchez, Technical University of Cartagena Fulgencio Valles, Technical University of Cartagena Juan Lopez, Technical University of Cartagena Andres Garcia, Technical University of Cartagena

Autonomous Underwater Vehicles II

5-Room 4B (Bahía Hall)

Wednesday, June 8 (5:00PM - 6:30PM)

Chair: Jin-Yeong Park, Maritime & Ocean Engineering Research Institute / KORDI

Control network architecture for an autonomous underwater vehicle. Divisamos project

Ricardo Pizá, *Universidad Politecnica de Valencia* Julián Salt, *Universidad Politécnica de Valencia* Angel Cuenca, *Universidad Politecnica de Valencia* Vicente Casanova, *Universidad Politecnica de Valencia*

Estimation of different acoustic signals usage efficiency for navigation systems of underwater autonomous vehicles

Ivan Karabanov, *Pacific National University* Igor Budinskiy, *Institute of Marine Technology Problems FEB RAS* Mihail Linnik, *Pacific National University* Andrei Mironov, *Pacific National University*

Cooperative distributed behaviours of an AUV network for asset protection with communication constraints

Andrea Caiti, *University of Pisa*Andrea Munafo', *University of Pisa*

On-board Underwater glider Real-time acoustic environment sensing

Alain Maguer, NATO Undersea Research Centre Alberto Dassatti, NATO Undersea Research Centre Piero Guerrini, NATO Undersea Research Centre Mike Van Der Schaar, Universitat Politècnica de Cataluña Michel Andre, Universitat Politècnica de Cataluña

Concept and demonstrator for modular pressure tolerant autonomous underwater vehicle

Christian Degel, Fraunhofer IBMT
Franz Josef Becker, Fraunhofer IBMT
Martin Heinz, Fraunhofer IBMT
Marc Schmieger, Fraunhofer IBMT
Manfred Moses, Fraunhofer IBMT
Matthias Molitor, Fraunhofer IBMT
Holger Hewener, Fraunhofer IBMT
Daniel Schmitt, Fraunhofer IBMT
Peter Weber, Fraunhofer IBMT
Robert Lemor, Fraunhofer IBMT

Acoustic Telemetry and Communication III

6-Room 5 (Bahía Hall)

Wednesday, June 8 (5:00PM - 6:30PM)

Chair: Konstantin Kebkal, EvoLogics GmbH

Underwater MAC protocol performance evaluation: From simulation to at-sea testing

Roberto Petroccia, *Università di Roma "La Sapienza"* Chiara Petrioli, *Università di Roma "La Sapienza"* John Potter, *NATO Undersea Research Centre*

Underwater acoustic communication channel characterization in the presence of bubbles and rough sea surfaces

Allan Boyles, Johns Hopkins University, Applied Physics Lab Allan Rosenberg, Johns Hopkins University, Applied Physics Lab Qinging Zhang, Johns Hopkins University, Applied Physics Lab

Channel prediction for adaptive modulation in underwater acoustic communications

Andreja Radosevic, University of California - San Diego
John Proakis, University of California, San Diego
Tolga Duman, School of Electrical, Computer and Energy Engineering, Arizona
State University
Milica Stojanovic, Northeastern University

Implementation of a micro-modem for underwater wireless sensor networks

Jun-Ho Jeon, *Gangneung-Wonju National University*Tae-Hee Won, *Gangneung-Wonju National University*Hunchul Cho, *Gangneung-Wonju National University*Sung-Joon Park, *Gangneung-Wonju National University*

Contention free MAC protocol based on priority in underwater acoustic communication

Jung-Il Namgung, Kookmin Univ.
Nam-Yeol Yun, Kookmin Univ.
Soo-Hyun Park, Kookmin Univ.
Chang-Hwa Kim, Gangneung-Wonju National University
Youngsun Ryuh, Korea Institute of Industrial Technology

Hui-Jin Cho. Kookmin Univ.

TECHNICAL PROGRAM

Thursday, June 9

Marine Communications and Technology I

1-Assembly Room

Thursday, June 9 (9:00AM - 11:00AM)

Co-Chairs: Zheng Peng, University of Connecticut

Christian Berger, Carnegie Mellon University

Study of pilot designs for Cyclic-Prefix OFDM on time-varying and sparse underwater acoustic channels

Christian Berger, Carnegie Mellon University Joao Gomes, Instituto Superior Tecnico José Moura, Carnegie Mellon University

Sea-trial results for Cyclic-Prefix OFDM with long symbol duration

Christian Berger, Carnegie Mellon University Joao Gomes, Instituto Superior Tecnico José Moura, Carnegie Mellon University

Design and implementation of a ð/4-DQPSK transmitter for maritime VHF digital communications

Kim Seung-Geun, MOERI/KORDI Sung Soyoung, MOERI/KORDI Yun Changho, MOERI/KORDI Lim Young-Kon, MOERI/KORDI

Agua-TUNE: A testbed for underwater networks

Zheng Peng, University of Connecticut
Son Le, University of Connecticut
Haining Mo, University of Connecticut
Michael Zuba, University of Connecticut
Yibo Zhu, University of Connecticut
Lina Pu, University of Connecticut
Jun Liu, University of Connecticut
Jun-Hong Cui, University of Connecticut

Proposal of a medium frequency offshore grid for identification of vessels sailing in high density maritime spanish routes

Alfonso López, *Universidad Católica de Ávila* Miguel Ángel Gutiérrez García, *Universidad Católica de Ávila* Andres Ortega Piris, *Universidad de Cantabria*

Fernando Blanco Silva, *Universidad de Santiago de Compostela* Manuel Ángel Graña López, *Universidad da Coruña*

Numerical and experimental study of the hydrodynamic phenomena in sea surface scattering

Slahedine Ben Khadra, ENSTA Bretagne Ali Khenchaf, ENSTA Bretagne

European Projects on Underwater Networks - 3

2-Room 1 (Bahía Hall)

Thursday, June 9 (9:00AM - 11:00AM)

Chair: Nirvana Meratnia, University of Twente, Pervasive Systems

CLAM: Collaborative embedded networks for submarine surveillance

Nirvana Meratnia, University of Twente, Pervasive Systems

Paul Havinga, University of Twente, Pervasive Systems

Paolo Casar

Chiara Petrioli, Università degli Studi di Roma

Knut Grythe, SINTEF

Thor Husoy, Kongsberg Maritime

Michele Zorzi, University of Padova

Underwater communications protocols and architecture developments at NURC

John Potter, NATO Undersea Research Centre

Alessandro Berni, NURC

Joao Alves, NURC

Diego Merani, NURC

Giovanni Zappa, NURC

Robert Been, NURC

On ARQ Strategies over random access protocols in underwater acoustic networks

Saiful Azad, University of Padova

Paolo Casari, University of Padova

Federico Guerra, University of Padova

Michele Zorzi, University of Padova

First output of the SOWFIA project: streamlining of ocean wave farms impact assessment

Cristina Huertas Olivares, Inabensa
Deborah Greaves, University of Plymouth
Brian Holmes, HMRC, University College Cork
Yago Torre-Enciso, Ente Vasco de la Energía
lan Bailei, University of Plymouth
Felix Danos, European Ocean Energy Association
Hakim Mouslim, Ecole Centrale de Nantes
Daniel Conley, University of Plymouth
Teresa Simas, Wave Energy Centre
Jan Sundberg, University of Uppsala
Victoria Osta Mora-Figueroa, University of Cadiz

Coastal Radars and Passive Observing Sensors

3-Room 2A (Bahía Hall)

Thursday, June 9 (9:00AM - 11:00AM)

Co-Chairs: Lucy Wyatt, *University of Sheffield*Malcolm Heron, *James Cook University*

Wind farm impacts on HF radar current and wave measurements in Liverpool Bay

Lucy Wyatt, *University of Sheffield*Alice Robinson, *University of Sheffield*M. Howarth, *National Oceanography Centre*

The data archive for the phased array HF radars in the australian coastal ocean radar network

Malcolm Heron, James Cook University Arnstein Prytz, James Cook University

Coherent marine radar measurements of ocean surface currents and directional wave spectra

Dennis Trizna, Imaging Science Research, Inc

Application of S-band nautical radar for ocean surface wave measurements

Hao-Yuan Cheng, Institute of Hydrological and Oceanic Sciences, National Central University

Hwa Chien, Institute of Hydrological and Oceanic Sciences, National Central University

Sea surface current measurements at long range using lower-band highfrequency radar

Eric Gill, Memorial University of Newfoundland Weimin Huang, Memorial University of Newfoundland

Implications of satellite sea-surface salinity observations for operational microwave radiometry

Eric Bayler, NOAA / NESDIS

Oceanographic Instrumentation, Sensors and Current Measurement Technology II

4-Room 3B (Bahía Hall)

Thursday, June 9 (9:00AM - 11:00AM)

Co-Chairs: Jaume Recolons, Universitat Politècnica de Cataluña

Kim Lau, MESTECH, National Centre for Sensor Research, DCU.

A new method for sea wave detection by using a speed log meter

Jaume Recolons, *Universitat Politècnica de Cataluña* Josep Torrents, *Universitat Politècnica de Cataluña*

Smart sensors for interoperable smart ocean

Daniel Toma, Technical University of Catalonia, UPC-SARTI

Tomas O'Reilly, MBARI

Joaquin Fernández, Technical University of Catalonia, UPC-SARTI

Kent Headley, MBARI

Antoni Lázaro, Technical University of Catalonia, UPC-SARTI

Duane Edgington, MBARI

Arne Bröring, 52North

Distributed sensing devices for monitoring marine environment

Kim Lau, MESTECH, National Centre for Sensor Research, DCU Dermot Diamond, MESTECH, National Centre for Sensor Research, DCU fiona Lau, MESTECH, National Centre for Sensor Research, DCU

Monitoring species using acoustic communications

David Gandul, UPC-SARTI

Erik Molino-Minero-Re, Universidad Politecnica Catalunya

Antoni Manuel, Universidad Politécnica de Cataluña

Joaquín del Río, Universidad Politécnica de Cataluña

Francesc Sarda, Institut de Ciencies del Mar

Jacopo Aguzzi, Institut de Ciencies del Mar

Guiomar Rollant, Institut de Recerca i Tecnologia Agroalimentaries

Systems and Observatories I

5-Room 4B (Bahía Hall)

Thursday, June 9 (9:00AM - 11:00AM)

Co-Chairs: Eric Delory, Plataforma Oceánica de Canarias

Pierre Leon, IFREMER

A new open cabled infrastructure in Medsea

Pierre LEON, IFREMER

Jean Francois Drogou, IFREMER

Claude Levegue, IFREMER

Pierre Valdy, IFREMER

Carl Cojak, INSU

Vincent RIGAUD, IFREMER

Henri Martinossi, IFREMER

damien Chenot, IFREMER

Dominique Santarelli, IFREMER

Anne Deschamps, Geosciences Azur

yann Hello, Geosciences Azur

Dominique Lefevre, CNRS

Zouhir Hafidi, INSU

jean jacques Destelle, cppm

Alain Massol. IFREMER

Christian Tamburini, CNRS

Karim Mahiouz, INSU

Yannick Lenault, INSU

Planning the installation of the European Multidisciplinary Sea-floor Observatory (EMSO): First approach using Geographic Information Systems (GIS)

Ismael Aymerich, Marine Technology Unit (UTM-CSIC)

Jaume Piera, Marine Technology Unit (UTM-CSIC)
Juanjo Dañobeitia, Marine Technology Unit (UTM-CSIC)

The PLOCAN Observatory: a multidisciplinary multiplatform observing system for the central-eastern Atlantic Ocean

Eric Delory, Plataforma Oceánica de Canarias

Joaquín Hernández-Brito, Plataforma Oceánica de Canarias

Octavio Llínas, Plataforma Oceánica de Canarias

The Gotland deep environmental sampling station in the Baltic Sea

Ralf Prien, Leibniz Institute for Baltic Sea Research

Detlef Schulz-Bull, Leibniz Institute for Baltic Sea Research

Walking on the sea side: Modelling and observational efforts of the Iberian Margin Observatory (RAIA)

Pablo Otero, Instituto Español de Oceanografia
Manuel Ruiz-Villarreal, Instituto Español de Oceanografia
Luz García-García, Instituto Español de Oceanografia
Martinho Marta-Almeida, Centro de Estudos do Ambiente e do Mar
Marcos Cobas, Centro de Supercomputación de Galicia - I. Español de Oceanografía
Gonzalo González-Nuevo, Instituto Español de Oceanografía
Jose Manuel Cabanas, Instituto Español de Oceanografía

Acoustic Telemetry and Communication IV

6-Room 5 (Bahía Hall)

Thursday, June 9 (9:00AM - 11:00AM)

Co-Chairs: Ilkka Karasalo, Swedish Defence Research Agency Xiaopeng Huang, Stevens Institute of Technology

On the performance of delay-tolerant routing protocols in underwater networks Muhammad Rahim, Department of Information Engineering, University of Padova Pado Casari, Department of Information Engineering, University of Padova

Paolo Casari, Department of Information Engineering, University of Padova Federico Guerra. Consorzio Ferrara Ricerche

Michele Zorzi, Department of Information Engineering, University of Padova

Effect of wind-generated bubbles on OFDM power loading for Time-varying shallow water acoustic channels with limited feedback

Xiaopeng Huang, Stevens Institute of Technology Victor Lawrence, Stevens Institute of Technology

A low cost and high efficient acoustic modem for underwater sensor networks

Antonio Sánchez, Universitat Politècnica de València Sara Blanc, *Universitat Politècnica de València* Pedro Yuste, *Universitat Politècnica de València* Juan Serrano, *Universitat Politècnica de València*

Time-domain modelling of turbo-coded underwater communication Ilkka Karasalo, Swedish Defence Research Agency

Performance assessment and EXIT chart analysis of IDMA-based underwater communications

Salah Aliesawi, School of Electrical, Electronic and Computer Engineering Charalampos Tsimenidis, School of Electrical, Electronic and Computer Engineering

Bayan Sharif, School of Electrical, Electronic and Computer Engineering Martin Johnston, School of Electrical, Electronic and Computer Engineering

Low-complexity doppler compensation for OFDM-based underwater acoustic communication systems

Ammar Abdelkareem, School of Electrical, Electronic and Computer Engineering Bayan Sharif, School of Electrical, Electronic and Computer Engineering Charalampos Tsimenidis, School of Electrical, Electronic and Computer Engineering Jeffrey Neasham, School of Electrical, Electronic and Computer Engineering Oliver Hinton, Newcastle University

Marine Communications and Technology II

1-Assembly Room

Thursday, June 9 (11:30AM - 1:30PM) Co-Chairs: Dale Green, Teledyne Benthos

Chin-Feng Lin, Department of Electrical Engineering/National

Taiwan Ocean University

Underwater radio frequency communications

Alejandro Beck, Nautilus Oceanica Manuel Gómez. Nautilus Oceanica Ian Crowther, WFS Technology Mark Rhodes, WFS Technology Mark Volanthen, WFS Technology

An MIMO-OFDM underwater acoustic multimedia communication

Chin-Feng Lin, Department of Electrical Engineering/National Taiwan Ocean University

Shun-Hsyung Chang, National Kaohsiung Marine Univerity

An optimized UUV communications framework for multi-vehicle arbitration

Andrew Bouchard, Naval Surface Warfare Center Panama City Division

Investigation of a full duplex acoustic link for a tetherless micro-ROV

Geraint Goodfellow, Newcastle University Jeffrey Neasham, Newcastle University Charalampos Tsimenidis, Newcastle University Oliver Hinton, Newcastle University Bayan Sharif, Newcastle University

Low overhead routing for underwater acoustic networks

Joao Alves, NATO Undersea Research Center Giovanni Zappa, NATO Undersea Research Center

Beyond underwater acoustic communications

Dale Green, *Teledyne Benthos* Ken Scussel, *Teledyne Benthos*

Airborne and Satellite Radar, SAR and Space Systems

3-Room 2A (Bahía Hall)

Thursday, June 9 (11:30AM - 1:30PM)

Chair: René Garello, Telecom Bretagne

Near-Nadir KA-BAND radar backscattering measurements over water surfaces, in preparation of the swot mission

Jean-François Nouvel, *ONERA*Joseph Martinot-Lagarde, *ONERA*Hélène Oriot. *ONERA*

Roger Fjortoft, CNES

GPS passive bistatic radar system in oceanic environment: detection performance estimation

Frederic Maussang, Telecom Bretagne

Rene Garello, Telecom Bretagne

Francois Soulat, CLS - Space Oceanography Division

Jean-Damien Desjongueres, CNES - DCT/SI/AR

Nadine Pourthie, CNES - DCT/SI/AR

Polarimetric characteristics of ships on RADARSAT-2 Data

Bo Wang, Telecom Bretagne

Bertrand Chapron, IFREMER

Grégoire Mercier, Telecom Bretagne

René Garello, Telecom Bretagne

Ming-Xia HE, Ocean Remote Sensing Institute

Detection and classification of man-made offshore objects in TerraSAR-X and RapidEye imagery: selected results of the DeMarine-DEKO project

Günter Saur, Fraunhofer IOSB

Stephane Estable, Astrium

Karin Zielinski, Astrium

Stefan Knabe, Astrium GEO-Information Services

Michael Teutsch, Fraunhofer IOSB

Maritime surveillance by integrating remote sensing and AIS:

A preliminary analysis

Maria Daniela Graziano, Second University of Naples Marco D'Errico, Second University of Naples Elena Razzano, Second University of Naples

Other

4-Room 3B (Bahía Hall)

Thursday, June 9 (11:30AM - 1:30PM)

Chair: Leif Persson, FOI

Advances in the specification and execution of underwater autonomous manipulation tasks

Mario Prats, Jaume-I University
Juan Carlos García, Jaume-I University
Javier Fernández, Jaume-I University
Raúl Marín, Jaume-I University
Pedro Sanz, Jaume-I University

Active floats for seismic acquisition spreads

Behzad Vahida, CGGVeritas Services - Marine Division - Engineering R&D

On-line metrics for assessment of fused tracking performance

Leif Persson, FOI Eva Dalberg, FOI Andris Lauberts, FOI Ron Lennartsson, FOI

Systems and Observatories II

5-Room 4B (Bahía Hall)

Thursday, June 9 (11:30AM - 1:30PM)

Co-Chairs: Jean-Philippe SCHNEIDER, ENSTA Bretagne

Andreas Marouchos, CSIRO - CMAR

Design of an advanced acoustic tide gauge for tsunami monitoring

Shijo Zacharia

R Srinivasan

Thamarai T.

Ramadass G.A

M.Aravindakshan Atmanand

Development of a stereo deepwater baited remote underwater video system (BRUVS)

Andreas Marouchos, CSIRO - CMAR Matthew Sherlock, CSIRO - CMAR Bruce Barker, CSIRO - CMAR Alan Williams. CSIRO - CMAR

Domain-specific modelling applied to smart sensors

Jean-Philippe Schneider, ENSTA Bretagne
Joël Champeau, ENSTA Bretagne
Dominique Kerjean, ENSTA Bretagne
Oussama Zein, Arts, Sciences and Technology University in Lebanon
Wes Auffret, IFREMER
Laurent Dufrechou, RTSys

Long-term underwater monitoring of seismic areas: design of an Ocean Bottom Seismometer with Hydrophone and its performance evaluation

Giorgio Mangano, Istituto Nazionale di Geofisica e Vulcanologia Antonino D'Alessandro, Istituto Nazionale di Geofisica e Vulcanologia Giuseppe D'Anna, Istituto Nazionale di Geofisica e Vulcanologia

Monitoring sediment dynamics at the boundary between the coastal zone and the continental shelf

Jorge Aranda, ICM-CSIC Marc Cervera, CTVG-UPC Antoni Làzaro, CTVG-UPC Alberto Monteys, ICM-CSIC Pere Alenyà, ICM-CSIC

Josefina Antonijuan, UPC

Acoustic Telemetry and Communication V

6-Room 5 (Bahía Hall)

Thursday, June 9 (11:30AM - 1:30PM)

Co-Chairs: Konstantinos Pelekanakis, National University of Singapore

Mauro Biagi, University of Rome, Sapienza

Underwater wireless video transmission for supervisory control and inspection using acoustic OFDM

Jordi Ribas Oliva, Massachusetts Institute of Technology Daniel Sura, Massachusetts Institute of Technology Milica Stojanovic, Northeastern University

Acoustic PPM image processing for underwater communications

Mauro Biagi, University of Rome, Sapienza

Characteristics of underwater acoustic communication channels in shallow water Tsih Yang, *Naval Research Laboratory*

Output SNR of time-reversal based underwater acoustic communications in different shallow water environments

Tsih Yang, Naval Research Laboratory

An algorithm for sparse underwater acoustic channel identification under symmetric Đ-stable noise

Konstantinos Pelekanakis, *National University of Singapore* Hongqing Liu, *National University of Singapore* Mandar Chitre, *National University of Singapore*

Node discovery protocol for Ad Hoc underwater acoustic networks

Ashish Patil, Northeastern University
Milica Stojanovic, Northeastern University

Oceanographic Instrumentation, Sensors and Current Measurement Technology III

7-Room 3A (Bahía Hall)

Thursday, June 9 (11:30AM - 1:30PM)

Co-Chairs: Joerg Seemann, Helmholtz Center Geesthacht

Andreas Rudolf, TU Darmstadt, Institute for Applied Physics

A Brillouin-LIDAR for remote sensing of the temperature profile in the ocean

- Progress towards the implementation

Andreas Rudolf, TU Darmstadt, Institute for Applied Physics Thomas Walther, TU Darmstadt, Institute for Applied Physics

Interoperable data management and instrument control experiences at OBSEA

Joaquin Fernández, *Technical University of Catalonia, UPC*Daniel TOMA, *Technical University of Catalonia, UPC*Tomás O'Reilly, *MBARI*Antoni Lazaro, *Technical University of Catalonia, UPC*Kent Headley, *MBARI*Arne Bröring, *52North*Duane Edgington, *MBARI*

Small and robust Ocean Bottom Seismometer (OBS) for long period active seismology

Shahram Shariat-Panahi, Technical University of Catalonia (UPC)
Normandino Carreras, Technical University of Catalonia (UPC)
Carola Artero, Technical University of Catalonia (UPC)
Antoni Mànuel Làzaro, Universidad Politecnica de Cataluña
Tim Owen, Carrack Measurement Technology
Erik Molino-Minero-Re, Universidad Politecnica de Cataluña

HF radar based current observation system in the german bight

Joerg Seemann, Helmholtz Center Geesthacht Klaus Gurgel, University of Hamburg Thomas Schlick, University of Hamburg Friedwart Ziemer, Helmholtz Center Geesthacht Stylianos Flampouris, Helmholtz Center Geesthacht Marius Cysewski, Helmholtz Center Geesthacht

NOTES				

EXHIBITOR BOOTH LIST

COMPANY	воотн #
Atlas Hydrographic GmbH	70
Bluefin Robotics	75
CLS Collecte Localisation Satellites	48
Codar Ocean Sensors, Ltd.	34
EMS, Sistemas de Monitorización Medio Ambiental, S.L.	71,72 y 73
Emu Limited	22
Eurotech Marine, S.L.	33
Evologics GmbH	67
Grafinta, S.A.	63
Grupo Sodercan, S.A.	45 y 46
Hawke Transit System, S.L.	36
IEEE/Oceanic Engineering Society	28
IH Cantabria, Universidad de Cantabria	15 y 16
Innova Oceanografía Litoral, S.L.	74
Ixblue SAS	35
Marine Technology Society	50
OCEANS 2013 (Bergen)	26
OCEANS'12 MTS/IEEE Hampton Roads & OCEANS'12 MTS/IEEE Yeosu	24
Office of Naval Research	54 y 55
QPS BV	18
Sea Tech Week	30
Sidmar Estudios y Servicios Oceanográficos, S.L.	49
Simrad Spain, S.L.	60, 61 y 62
Sondara Solucions SLNE	20
U.C. Dpto. TEISA Grupo de Informática y Automática	17
Universitat de Girona	56
Vázquez y Torres Ingeniería, S.L.	66

OCEANS 2011 EXHIBITOR PROFILES

Atlas Hydrographic GmbH

Booth: 70

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ATLAS HYDROGRAPHIC GmbH is engaged in the design, manufacture, sales and support of innovative hydrographic survey systems.

We are specialised in integrating scientific instrumentation systems for research vessels and sonar-to-chart solutions for customers in the field of hydrography. Our single beam echosounders ATLAS DESO, multibeam echosounders FAN-SWEEP and HYDROSWEEP as well our parametric sub-bottom profilers PARA-SOUND are well known in worldwide marine society.

Bluefin Robotics

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Bluefin Robotics develops, builds, and operates Autonomous Underwater Vehicles (AUVs) and related technologies for defense, commercial, and scientific customers worldwide. We offer a full range of modular, free-flooded AUV platforms in standard and custom configurations as well as pressure-tolerant rechargeable battery packs for subsea applications. Bluefin Robotics provides expertise for the full lifecycle AUVs including research and development, technology integration, full-scale manufacturing, platform training, and operations support. Get a Bluefin and get your data. www.bluefinrobotics.com.

CLS Collecte Localisation Satellites

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CLS, a subsidiary of the French Space Agency, is the exclusive operator of the Argos satellite system and is an Iridium value-added reseller (VAR). CLS provides satellite-based data acquisition, positioning and engineering services. CLS: the satellite service provider for the met-ocean community.

Codar Ocean Sensors, Ltd.

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CODAR Ocean Sensors offers the SeaSonde® HF radar system for real-time, continuous ocean surface current mapping and wave monitoring. The SeaSonde is considered the backbone of many regional ocean observing systems and is more widely used internationally inside operational scenarios. It features convenient operation from shore or platform, with no equipment in water. Product enhancements are added continually, allowing it to remain the most advanced HF radar system available. A similar product, called RiverSonde®, has been recently been developed for river environment.

EMS, Sistemas de Monitorización Medio Ambiental, S.L.U.

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EMS is a leading oceanographic instruments, systems and services company with offices in Barcelona and Paris. EMS represents leading instrument and uw-technology manufacturers, specializing in sensors, vehicles, platforms, infrastructure components and associated services. EMS represents: Sea-Bird Electronics, WET-Labs, Teledyne RD Instruments, Biospherical, Turner Designs, Chelsea Technologies, Sequoia Scientific, Ocean Sciences, Technicap, Link-Quest, Deep Sea Power and Light, VideoRay, Deep Ocean Engineering, International Submarine Engineering, Bluefin Robotics, Liquid Robotics, Flotation Technologies, Falmat Cables, Sound Ocean Systems, Romor Ocean Solutions, Xeostech, ATLAS Hydrographic. EMS is a capable systems integrator and builds sensor networks, buoy systems and supplies complete oceanographic shipborne system packages.

Emu Limited

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EMU Limited — renowned experts in offshore and coastal marine surveys with high class consultancy skills to benefit clients from all fields. We supply our services to support renewable energy projects, oil and gas, marine aggregates, power companies, water utilities, ports and harbours, coastal engineers, facilities management and leisure sectors. SemSorGrid4Env — Semantic Sensor Grids for Rapid Application Development for Environmental Management — an EU FP7 funded project. The application sources and uses a variety of data, in real-time and from databases to provide real-time monitoring and short term sea state and flood forecasts for coastal management.

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Ultrasonic sea devices as, doppler current meters, Trawl Camera, underwater lights, Size sounders, Ultrasonic directional Wave meter and anemometers for Marine research, Industry, ports and coast surveillance.

Evologics GmbH

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Grafinta, S.A.

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GRAFINTA S.A. founded in 1964 offers the most innovate products for Surverying and Mapping, Geodesy, Hydrography, Civil Engineering, Agriculture, Defense Systems, Oceanography, etc.

GRAFINTA S.A. has a specialized an certified quality control laboratory, so that the customers can extend the warranty and quality offered by our suppliers and demanded by our customers.

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Grupo Sodercan, S.A.

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Grupo SODERCAN is a group of public companies whose purpose is to promote and contribute actively to the creation of a socio-corporate environment that encourages investment in the Cantabrian industrial network and develops innovation and competitive improvement. Furthermore, Grupo SODERCAN aims to generate social and environmental value in the companies, administration and society in general. SEA OF INNOVATION CANTABRIA CLUSTER is a pioneer cluster, a leader and a technological reference in the marine energy sector. Comprising more than 40 companies and 15 research organizations, its main goal is the comprehensive development of advanced projects in the field of marine energy in order to propose innovative solutions to the challenges in the industry. Sea of Innovation Cantabria Cluster is designed to integrate all actors operating in the marine energy sector in Cantabria, to promote Cantabria as a center of excellence within the national and international market

Hawke Transit System, S.L.

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HAWKE TRANSIT SYSTEM is a modular sealing system for cables and pipes against fire, water, gas, etc. This system offers cost effectiveness, speed of assembly, flexibility and total inspectability of the installation. This system could be used in new installations as in old ones.

Hawke Transit System has offices in UK, Singapore and Spain and many distributors around the world

IEEE/Oceanic Engineering Society

Booth: 28

Website: www.ieeeoes.org

The Oceanic Engineering Society (OES) of the Institute of Electrical and Electronics Engineers, Inc. (IEEE) seeks to advance the science and technology of Ocean Engineering. Its objectives are scientific, literary, and educational in character. The Society strives for the advancement of the theory and practice of electro-technology applied to the ocean environment not only by ocean engineers but also by individuals in allied branches of engineering and related arts and sciences. The Society maintains a high level of professional standards among its members and affiliates and through them promotes technical excellence and actively encourages

the exchange of information through conferences, meetings, workshops and publications. Stop by the IEEE/OES booth for membership information.

Innova Oceanografía Litoral, S.L.

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INNOVA oceanografía litoral SL is a Spanish company devoted to services and sales in our local oceanographic market. We care of a range of research and consultant companies interested in dynamical oceanography (currents, waves, tides and winds). Our company, founded on 1997, is specialized in oceanographic services and supplies for monitoring and control dynamic variables at sea. We are also committed to technical developments and NextGen tools in order to reduce the gap between the active industry and the busy end-users who cannot be aware of so many new developments.

Instituto de Hidráulica Ambiental de la Universidad de Cantabria

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The ENVIRONMENTAL HYDRAULICS INSTITUTE "IH CANTABRIA", is a joint research centre between the University of Cantabria and the Foundation for Environmental Hydraulics Institute. IH Cantabria is made up of approximately one hundred fifty researchers, with over twenty years of expertise in water-related fields and focuses its activities on three main pillars: research & development, consultancy and education & training activities.

The mission of IH Cantabria is to become an international reference centre specialising in basic and applied research as well as focusing on the development of studies, methodologies, and tools for the management of aquatic ecosystems including the development of marine renewable energies.

oceans 2011 IEEE/OES Santander, Spain

Ixblue SAS

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IXSEA offers new products and turnkey solutions for the Offshore Industry, Marine Construction, and Survey Industry (ROVs, Lay & construction barges, IMR & Survey vessels, DP vessels, FPSOs, etc.). At Oceans'11, we present:

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- OCTANS: surface and subsea applications (0 to 6000m depth)
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Acoustic Positioning, and Metrology

- GAPS & POSIDONIA :calibration free; long distance USBL
- OCEANO: acoustic releases
- RAMSES : acoustic metrology

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- SHADOWS Mapping Sonar: large area seafloor mapping tool
- ECHOES: new range of Sub-Bottom Profilers
- DELPH Software suite: sonar, seismic, magnetometer data interpretation SW

Marine Technology Society (MTS)

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The International Marine Technology Society offers extraordinary resources and networking opportunities to ocean engineers, technologists, government, industry and academia. MTS's passion for the advancement and application of marine technology assists members through 28 specialized committees (seafloor technologies, ocean observing, underwater vehicles, marine security and more), conferences, workshops, a professional journal, and newsletters. MTS maintains a website with news for and about the maritime community.

OCEANS'12 MTS/IEEE Hampton Roads

Booth: 24

OCEANS'12 MTS/IEEE Yeosu

Booth: 26

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OCEANS '12 MTS/IEEE YEOSU will be held in 'The Ocean Resort' which is located in beautiful harbor on May 21-24, 2012.

With the theme of 'Living Ocean and Coast: Diversity of Resources and Sustainable Activities'. The OCEANS'12 YEOSU coincides with Expo 2012 Yeosu Korea. Based on the coexistence of the oceans and humankind, Expo 2012 Yeosu Korea will propose the 'Blue Economy' as the basis for the prudent use and preservation of the sea. This conference and exhibition will be an attractive, stimulating and unforgettable event. We hope you can join us.

OCEANS 2013 (Bergen)

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IEEE Norway Section warmheartedly welcomes you to the OCEANS'13 MTS/IEEE "The Challenges of the Northern Dimension".

The conference will be hosted in the 'Gateway to the Norwegian Fjords', in the coastal city of Bergen, Norway, June 11-14th 2013.

Office of Naval Research

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In building and fostering international connections, ONR Global propels the execution of long-range strategic efforts that address the future needs of the naval fleet and forces and international partners. ONRG's associate directors promote collaboration with international scientists while its science advisors identify fleet/ force needs and implement technology solutions. Both serve as the chief of naval research's science ambassadors abroad.

QPS BV

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QPS is a software house with its roots in the hydrographic and offshore industry. QPS recently acquired IVS 3D, the makers of Fledermaus.

Software developments are focused on the system integration and systems used for hydrographic surveys, seafloor mapping, data processing and visualization, and ENC production. QPS is the only software manufacturer in the world which covers the total hydrographic data flow from data acquisition through data validation, visualization and cleaning up to S-57 ENC production. QPS is seen as one of the market leaders in this field. Recently QPS carried out very successfully trials with combined laser scanning and multibeam and various mobile laser scanning projects used QINSy for real-time data acquisition.

Qualitas Remos

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QUALITAS REMOS is a leading company in providing technology and data intensive ocean observing and IT solutions for the environmental protection, offshore and renewables, operational oceanography and maritime sectors with activity in Europe, Africa and the Middle East. Special focus is placed on HF RADAR ocean observing by means of SEASONDE in alliance with CODAR OCEAN SENSORS and to the implementation of information management and tailored decision support tools by means of the PORTUS by QUALITAS system.

Sea Tech Week

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Sidmar Estudios y Servicios Oceanográficos, S.L.

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SIDMAR®, Estudios y Servicios Oceanográficos, S.L. focuses its activities in the field of marine science and environmental and marine technology. Offers oceanographic turnkey services to its customers, among them:

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- R + D, as a way to provide and generate knowledge.

Works for public and private entities throughout Spain for over fifteen years, making it a pioneer in the sector.

Simrad Spain, S.L.

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Kongsberg Maritime - Subsea Division operates predominantly in offshore oil and gas markets, surveying (seabed mapping, surveying and investigations), defence, fisheries and oceanography. The products are based on hydroacoustics, sensor knowledge, advanced signal processing and underwater engineering.

Sondara Solucions SLNE

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SONDARA SOLUCIONS is a company founded in 2007 focused on oceanography and environmental projects. SONDARA SOLUCIONS was created by a multidisciplinary scientific professional group of people with expertise in different areas of research and instrumentation, computing and rational design. Besides being dealer of oceanographic products, SONDARA SOLUCIONS offers the following services: technical support, construction of metallic structures, implementation of telemetry systems and software development for acquisition and treatment data.

Universidad de Cantabria. Dpto. TEISA Grupo de Informática y Automática

Booth: 17

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Activity Description: Modeling, Optimization and Control. Guidance, navigation and control (GNC) of Marine Vehicles. Remote Marine Laboratory (MRL). Underwater Robotics. Underwater Inspection. Underwater Acoustic Image Processing.

Products and Services: Monitoring, Automation and Control. Innovation, Development, Production and Support for Product Lifecycle Management (PLM) with Software Technology CAD, CAM, CAE, Digital Manufacturing and Product Data Management (PDM). Vehicle and Marine Systems Experimentation. Underwater Search & Location. Inspection, Monitoring and Underwater Surveillance. Ship underwater body and other underwater structures inspection. Film recording and Underwater Acoustic Images.

Universitat de Girona

Booth: 56

CIRS - Centre d' Investigació en Robòtica Submarina. Parc Científic i Tecnològic

UdG

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The Computer Vision and Robotics Research Centre (ViCOROB) at the University of Girona (Spain) develops research in the fields of: Underwater Vision and Underwater Robotics, Medical imaging, Multimedia Imaging, Mobile Robotics and 3D perception. The team is composed of 72 researchers on different fields: Computer Engineering, Industrial Engineering, Electronical Engineering as well as Mathematics and Managment Staff.

ViCOROB has lately developed in its Underwater Robotics Research Centre (CIRS), at the Scientific and Technological Park of the UdG, an autonomous underwater vehicle (AUV) capable to navigate 500m deep (GIRONA 500). The GIRONA 500 is a compact and lightweight research platform with hovering capabilities, which can fulfill the particular needs of any application by means of mission-specific payloads and a reconfigurable propulsion system.

Vázquez y Torres Ingeniería, S.L.

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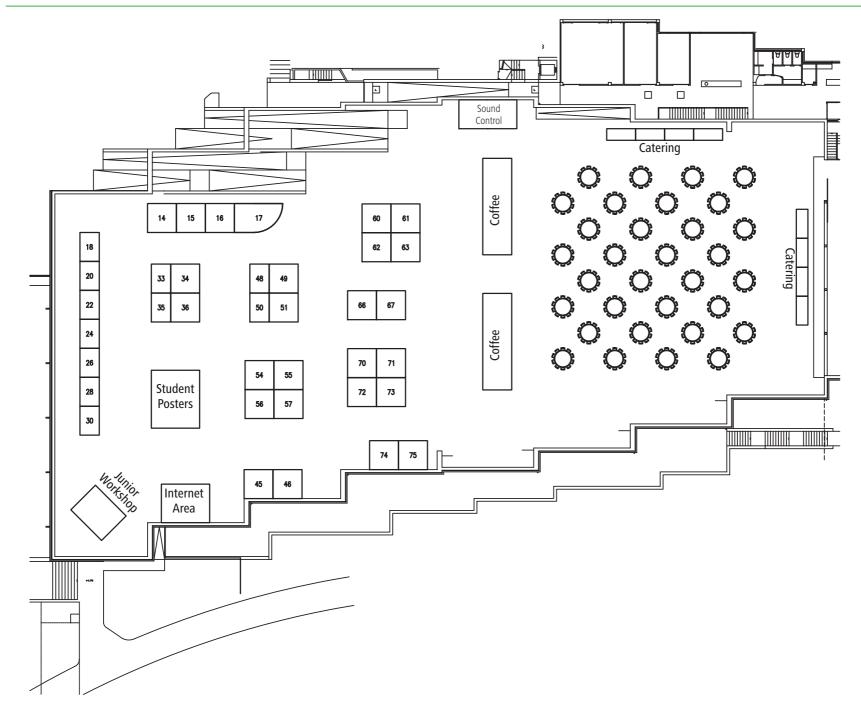
Email: egardeta@vtisl.com Website: www.vtisl.com

VTI designs and supplies custom made test systems for Universities and R+D laboratories and departments of technological companies.

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