

I. Postulates and Lorentz transformations

Principle of special relativity: The laws of Nature are invariant under a particular group of space-time transformations. These are the Lorentz transformations.

Denoting coordinates as $X^a = (\underbrace{x^0}_{ct}, \underbrace{x^1, x^2, x^3}_{\vec{x}})$, the Lorentz group has an action

$$X'^a = \underbrace{\Lambda^a_b}_{\text{cte}} X^b$$

with

$$\Lambda^a_c \Lambda^b_d \eta_{ab} = \eta_{cd} \iff \Lambda^t \eta \Lambda = \eta$$

for the Minkowski metric

$$\eta_{ab} = \eta_{ba} = \begin{bmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

$$\Lambda \in O(1,3)$$

"Lie group"

* Line element (proper time): Lorentz transformations leave invariant the element line

$$ds^2 = -d\tau^2 \equiv \text{"proper time"}$$

$$ds^2 = \eta_{ab} dx^a dx^b = -c^2 dt^2 + d\vec{x}^2$$

Proof: $ds'^2 = \eta_{ab} dx'^a dx'^b = \underbrace{\eta_{ab} \Lambda^a_c \Lambda^b_d}_{\eta_{cd}} dx^c dx^d = ds^2$

Important: Light propagation $\Leftrightarrow ds^2 = 0$

\Rightarrow Michelson-Morley experiment: speed of light is the same in all inertial frames related by Lorentz transformations.

* Lorentz transformations are the most general coordinate transformations $x \rightarrow x'$ leaving invariant ds^2

$$ds'^2 = \eta_{ab} dx'^a dx'^b = \eta_{ab} \frac{\partial x'^a}{\partial x^c} \frac{\partial x'^b}{\partial x^d} dx^c dx^d$$

$$\stackrel{!}{=} \eta_{cd} dx^c dx^d \Rightarrow \eta_{cd} = \eta_{ab} \frac{\partial x'^a}{\partial x^c} \frac{\partial x'^b}{\partial x^d}$$

This must hold !!
(*)

Differentiating (*) with respect to x^e :

$$0 = \eta_{ab} \frac{\partial^2 x'^a}{\partial x^e \partial x^c} \frac{\partial x'^b}{\partial x^d} + \eta_{ab} \frac{\partial x'^a}{\partial x^c} \frac{\partial^2 x'^b}{\partial x^e \partial x^d} \quad \left. \begin{array}{l} \text{free} \\ \text{indices} \\ (c, e, d) \end{array} \right\}$$

Adding $+0$ and subtracting -0

$$0 = \eta_{ab} \left[\frac{\partial^2 x'^a}{\partial x^e \partial x^c} \frac{\partial x'^b}{\partial x^d} + \frac{\partial x'^a}{\partial x^c} \frac{\partial^2 x'^b}{\partial x^e \partial x^d} \right. \\ \left. + \frac{\partial^2 x'^a}{\partial x^c \partial x^e} \frac{\partial x'^b}{\partial x^d} + \frac{\partial^2 x'^b}{\partial x^c \partial x^d} \frac{\partial x'^a}{\partial x^e} \right. \\ \left. - \frac{\partial^2 x'^a}{\partial x^d \partial x^c} \frac{\partial x'^b}{\partial x^e} - \frac{\partial^2 x'^b}{\partial x^d \partial x^e} \frac{\partial x'^a}{\partial x^c} \right]$$

NOTE: wavy cancel because $\eta_{ab} = \eta_{ba}$

$$= 2 \frac{\partial^2 x'^a}{\partial x^e \partial x^c} \underbrace{\frac{\partial x'^b}{\partial x^d}}_{\neq 0} \underbrace{\eta_{ab}}_{\neq 0} \Rightarrow \underbrace{\frac{\partial^2 x'^a}{\partial x^e \partial x^c}}_{=0}$$

Solution :

$$\text{Lorentz transformation : } x'^a = \underbrace{\Lambda^a_b}_{\text{Lorentz}} x^b + \underbrace{C^a}_{\text{Translation (new origin)}}$$

"Poincaré group"

$$\Lambda^a_b, C^a = \text{cte}$$

[6+4=10 parameters]

NOTE: If $ds^2 = 0 \Rightarrow$ 15 parameters !!
[conformal group].

* Recall that $\Lambda^t \eta \Lambda = \eta \Rightarrow |\Lambda|^2 = 1$

* Orthochronous : $\Lambda^0_0 \geq 1 \Rightarrow \begin{cases} |\Lambda| = +1 : \text{Proper Lorentz} \\ |\Lambda| = -1 : \text{Improper Lorentz} \end{cases}$
↳ preserve direction of time

NOTE: $|\Lambda| = +1$ is the proper case connected with the identity \mathbb{I} and thus $\Lambda \in \text{SO}(1,3)$.

* Subcases of the proper Lorentz transformations :

a) Rotations : $\Lambda = \left[\begin{array}{c|ccc} 1 & 0 & 0 & 0 \\ \hline 0 & R^i_j & & \\ \hline 0 & & & \end{array} \right]$ with $|R|=1$ and $R^t \mathbb{I} R = \mathbb{I}$
[Subgroup]

\Rightarrow Rotations + Translations = Galileo group

• Setting $\vec{v} = 0$:

$$\left. \begin{array}{l} dx'^i = R^i_j dx^j \\ dt' = dt \end{array} \right\} \frac{dx'^i}{dt'} = \sigma_i' = R_i^j \sigma_j = R_i^j \frac{dx^j}{dt}$$

b) Boosts : $\Lambda^a_b = \left[\begin{array}{c|c} \Lambda^a_0 & \Lambda^a_j \\ \hline \Lambda^i_0 & \Lambda^i_j \end{array} \right]$ with
[Not a subgroup]

components

\rightarrow "Lorentz factor"

$$\Lambda^0_0 = \gamma \equiv \frac{1}{\sqrt{1 - \frac{|\vec{v}|^2}{c^2}}}, \quad \Lambda^0_j = \gamma \frac{v_j}{c}, \quad \Lambda^i_0 = \gamma \frac{v_i}{c}$$

$$\text{and } \Lambda^i_j = \delta_{ij} + \sigma_i \sigma_j \frac{(\gamma - 1)}{|\vec{v}|^2}$$

in terms of 3 free parameters v_i .

Important: This parameterisation of the boosts reproduces the change of frame $dx'^a = \Lambda^a_b dx^b$ from an observer O seeing a particle at rest, to an observer O' seeing the particle moving with velocity $\vec{v} = (v_x, v_y, v_z)$. Notice the $|\vec{v}| \rightarrow c$ pathology to put light at rest !!

* Meaning of the Lorentz factor?

$$\begin{aligned}
 \underbrace{d\tau^2}_{\text{"proper time"}} &= -dS^2 = c^2 dt^2 - d\vec{x}^2 \Rightarrow d\tau = \sqrt{c^2 dt^2 - d\vec{x}^2} \\
 &= \sqrt{c^2 dt^2 - \frac{d\vec{x}^2}{dt^2} dt^2} \\
 \text{Momentarily Inertial Frame (MIF)} \\
 ds^2 &= -d\tau^2 + \underbrace{d\vec{x}^2}_0 = -d\tau^2 \\
 &= \sqrt{c^2 dt^2 - c^2 \frac{|\vec{v}|^2}{c^2} dt^2} \\
 &= \sqrt{1 - \frac{|\vec{v}|^2}{c^2}} c dt \\
 &= \frac{c}{\gamma} dt
 \end{aligned}$$

$$\Rightarrow \boxed{\gamma \cdot d\tau = c \cdot dt}$$

Rescaling of the time of an observer with respect to the "proper time"

* Energy and momentum

$$\begin{aligned}
 u^a &= \gamma (c, \vec{v}) \Leftrightarrow u^a \equiv \text{proper velocity} \\
 p^a &= m c \frac{dx^a}{d\tau} \Rightarrow \left\{ \begin{aligned} p^0 &= m \cdot c^2 \frac{dt}{d\tau} = \gamma m c \equiv \frac{E}{c} \text{ (energy)} \\ \vec{p} &= m c \frac{d\vec{x}}{d\tau} = m \gamma \frac{d\vec{x}}{dt} = m \gamma \vec{v} \end{aligned} \right.
 \end{aligned}$$

NOTE: If $\frac{|\vec{v}|}{c} \ll 1 \Rightarrow \gamma = \frac{1}{\sqrt{1 - \frac{|\vec{v}|^2}{c^2}}} \approx 1 + \frac{1}{2} \frac{|\vec{v}|^2}{c^2} + \frac{3}{8} \frac{|\vec{v}|^4}{c^4} + \dots$

NOTE: $-d\tau^2 = dx^a dx_a \Rightarrow u^a u_a = -c^2$

and so:

$$\begin{aligned}
 E &= \gamma m c^2 = \underbrace{m c^2}_{\text{Rest energy}} + \underbrace{\frac{1}{2} m |\vec{v}|^2}_{\text{Kinetic energy}} + \dots \\
 \vec{p} &= m \gamma \vec{v} = m \vec{v} + \dots
 \end{aligned}$$

At lowest order one recovers the non-relativistic results!!

* Dispersion relation $E(|\vec{p}|)$: Starting from

$$E = \gamma m c^2 \quad \text{and} \quad \vec{p} = m \gamma \vec{v}$$

one finds that

$$E^2 = \gamma^2 m^2 c^4 = m^2 c^4 \left(1 - \frac{|\vec{v}|^2}{c^2}\right)^{-1} \Rightarrow \frac{|\vec{v}|^2}{c^2} = 1 - \frac{m^2 c^4}{E^2}$$

and then

$$|\vec{p}|^2 = m^2 \gamma^2 |\vec{v}|^2 = \frac{E^2}{c^4} \left(1 - \frac{m^2 c^4}{E^2}\right) c^2 = \frac{E^2}{c^2} - m^2 c^2$$

$$\Rightarrow E^2 = m^2 c^4 + |\vec{p}|^2 c^2$$

$$\Rightarrow E(\vec{p}) = c \sqrt{m^2 c^2 + |\vec{p}|^2}$$

"De Broglie dispersion relation"

* Energy and momentum ($m=0$ and $|\vec{v}|=c$): This is the special case of "photons". In this case:

$$\frac{|\vec{v}|}{c} = 1 \Rightarrow \gamma = \infty \quad \text{and} \quad m = 0$$

so

$$\vec{p} = m \cdot \gamma \cdot \vec{v} \quad (\text{indeterminate})$$

$$E = \gamma m c^2 \quad (\text{indeterminate})$$

but the dispersion relation is still valid $\Rightarrow E = c |\vec{p}|$

II. Vectors and tensors

Objects in the theory of special relativity transform covariantly under Lorentz transformations.

* Coordinates and partial derivatives:

$$x'^a = \Lambda^a_b x^b \quad \Leftrightarrow \quad \frac{\partial}{\partial x'^a} = \underbrace{\frac{\partial x^b}{\partial x'^a}}_{\Lambda_a^b} \frac{\partial}{\partial x^b} = \Lambda_a^b \frac{\partial}{\partial x^b}$$

NOTE: Recall that $\Lambda^a_b = \frac{\partial x'^a}{\partial x^b}$

so that

$$\Lambda_a^b = \eta_{ac} \eta^{bd} \Lambda^c_d$$

with $\eta_{ab} = \eta^{ab}$ and $\eta_{ab} \eta^{ac} = \delta_a^c$.

As a result:

$$\Lambda_a^b \Lambda^a_c = \underbrace{\eta_{ae}}_{\downarrow} \eta^{bf} \underbrace{\Lambda^e_f \Lambda^a_c}_{\downarrow} = \eta_{cf} \eta^{bf} = \delta_c^b$$

$\Rightarrow \Lambda_x^*$ and $\Lambda^* x$ are transpose inverse of each other.

* Covariant and contravariant vectors: Contravariant V^a and covariant vectors V_a are well-defined objects

that relate as

$$V_a = \eta_{ab} V^b \iff V^a = \eta^{ab} V_b$$

Under a Lorentz transformation one has

$$V_{a'}(x') = \Lambda_{a'}^b V_b(x) \quad \text{and} \quad V^{a'}(x') = \Lambda^a_{b'} V^b(x)$$

so that full-contractions are Lorentz-invariant quantities

$$u^a V_a = \Lambda^a_b u^b \Lambda_a^c V_c = u^b V_c \underbrace{\Lambda^a_b \Lambda_a^c}_{\delta_b^c} = u^b V_b$$

NOTE: $\partial_a V^a$ (divergence) is Lorentz-invariant.

NOTE: d'Alembertian is a Lorentz-invariant operator

$$\square = \eta^{ab} \frac{\partial}{\partial x^a} \frac{\partial}{\partial x^b} = \vec{\nabla}^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}$$

* **Mixed tensors**: General tensors can be constructed transforming multilinearly under Lorentz transformations

$$T^{c'}_{a'b'}(x') = \Lambda^c_d \Lambda_{a'}^e \Lambda_{b'}^f T^d_{ef}(x)$$

General mixed tensors satisfy:

- **Linearity**: $T^a_b \equiv \alpha \underbrace{R^a_b}_{\text{tensor}} + \beta \underbrace{S^a_b}_{\text{tensor}}$ is a tensor.

- Direct product : $T^a_b{}^c \equiv \underbrace{A^a_b}_{\text{tensor}} \underbrace{B^c}_{\text{tensor}}$ is a tensor.

- Contraction : $T^{ab} = \underbrace{T^a_c{}^{bc}}_{\text{tensor}}$ is a tensor.

- Differentiation : $T_a{}^{bc} \equiv \underbrace{\frac{\partial}{\partial x^a}}_{\text{tensor}} \underbrace{T^{bc}}_{\text{tensor}}$ is a tensor. [direct product]

* Lorentz-invariant tensors : There are three invariant tensors under Lorentz transformations

- The metric tensor : $\eta'_{ab} = \underbrace{\Lambda_a^c \Lambda_b^d}_{\Lambda \eta \Lambda^t} \eta_{cd} = \eta_{ab}$

- The Levi-Civita tensor : $\epsilon^{abcd} = \begin{cases} +1 & : \text{even permut of } 0123 \\ -1 & : \text{odd permut of } 0123 \end{cases}$

$$\Lambda^a_e \Lambda^b_f \Lambda^c_g \Lambda^d_h \epsilon^{efgh} \propto \epsilon^{abcd}$$

Looking at the component:

↳ must be fully antisym
 \Rightarrow proportional to ϵ itself !!

$$\begin{aligned} \epsilon^{0123} &= \Lambda^0_e \Lambda^1_f \Lambda^2_g \Lambda^3_h \epsilon^{efgh} \\ &= \det(\Lambda) \epsilon^{0123} = \epsilon^{0123} \end{aligned}$$

↳ if Λ is a "proper" Lorentz transf.

- The zero tensor with arbitrary pattern of indices.

NOTE: $\epsilon^{abcd} = \eta_{ae} \eta_{bf} \eta_{cg} \eta_{dh} \epsilon^{efgh} = -\epsilon^{abcd}$

\downarrow
 $|\eta| = -1$

Important: If two tensors have the same index structure and are the same for an observer in a coordinate system \Rightarrow They are the same for any other inertial observer.

\Rightarrow The statement that a tensor vanishes is a Lorentz-covariant statement !!

III. Classical electrodynamics

Maxwell's equations for electromagnetism can be written in a covariant form

$$\begin{aligned} \vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \quad [\text{Gauss}] & \text{and} & \quad \vec{\nabla} \cdot \vec{B} = 0 \quad [\text{Gauss}] \\ \vec{\nabla} \times \vec{B} &= \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad (*) \quad [\text{Ampère}] & & \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad [\text{Faraday}] \quad (**) \end{aligned}$$

where $\rho \equiv$ elec. charge density, $\vec{J} \equiv$ elec. current density and $\begin{cases} \epsilon_0 \equiv \text{permittivity} \\ \mu_0 \equiv \text{permeability} \end{cases}$

Question: How do \vec{E} and \vec{B} transform under Lorentz?

Let us introduce the electromagnetic field strength

$$F^{ab} \equiv \begin{pmatrix} 0 & \frac{E_1}{c} & \frac{E_2}{c} & \frac{E_3}{c} \\ -\frac{E_1}{c} & 0 & B_3 & -B_2 \\ -\frac{E_2}{c} & -B_3 & 0 & B_1 \\ -\frac{E_3}{c} & B_2 & -B_1 & 0 \end{pmatrix} = -F^{ba}$$

Then $F^{0i} = \frac{E_i}{c}$ and $F^{ij} = \epsilon^{ijk} B^k$ so that

$$(*) : \frac{\partial}{\partial x^a} F^{ab} = \partial_a F^{ab} = -\mu_0 J^b \quad \text{Prediction !!}$$

$$[\text{Gauss}] \quad b=0 : \frac{\partial}{\partial x^i} F^{i0} = -\mu_0 J^0 \Rightarrow \vec{\nu} \cdot \vec{E} = c \mu_0 J^0 = \mu_0 c^2 \cdot \rho = \frac{\rho}{\epsilon_0}$$

$$[\text{Ampère}] \quad b=j : \frac{1}{c} \frac{\partial}{\partial t} F^{0j} + \frac{\partial}{\partial x^i} F^{ij} = -\mu_0 J^j$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial}{\partial t} E^j + \epsilon^{ijk} \frac{\partial}{\partial x^i} B^k = -\mu_0 J^j$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial}{\partial t} E^j - \epsilon^{jik} \frac{\partial}{\partial x^i} B^k = -\mu_0 J^j$$

$$\Rightarrow \vec{\nu} \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} + \mu_0 \vec{J} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

where $J^a \equiv (c \cdot \rho, \vec{J})$

$$(**) \quad \epsilon^{abcd} \frac{\partial}{\partial x^b} F_{cd} = 0 \quad \text{with} \quad F_{cd} = \eta_{ca} \eta_{db} F^{ab}$$

$$[\text{Gauss}] \quad a=0 : \epsilon^{0ijk} \frac{\partial}{\partial x^i} F_{jk} = 0 \Rightarrow \underbrace{\epsilon^{ijk} \epsilon_{jkl}}_{2 \delta^{il}} \frac{\partial}{\partial x^i} B^l = 0$$

$$\Rightarrow \vec{\nu} \cdot \vec{B} = 0$$

$$[\text{Faraday}] \quad a=i : \quad \epsilon^{i0jk} \frac{1}{c} \frac{\partial}{\partial t} F_{jk} + \epsilon^{ij0k} \frac{\partial}{\partial x_j} F_{0k} + \epsilon^{ijk0} \frac{\partial}{\partial x_j} F_{k0} = 0$$

$$- \underbrace{\epsilon^{ijk} \epsilon_{jkl}}_{2\delta^i_l} \frac{1}{c} \frac{\partial}{\partial t} B^l + 2 \epsilon^{ijk} \frac{\partial}{\partial x_j} \left(-\frac{E^k}{c} \right) = 0$$

$\hookrightarrow F_{0i} = -F^{0i}$

$$\Rightarrow \frac{\partial}{\partial t} \vec{B} + \vec{\nabla} \times \vec{E} = 0$$

$$\Rightarrow \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

"dual"
 \hookrightarrow field strength

Important: $\epsilon^{abcd} \partial_b F_{cd} = 0 \iff \partial_b \tilde{F}^{ab} = 0$ with $\tilde{F}^{ab} \equiv \epsilon^{abcd} F_{cd}$

* Bianchi form of Gauss-Faraday law: It will be useful to consider the alternative expression

$$\underbrace{\epsilon_{aefg} \times \epsilon^{abcd}}_{\times \delta_{efg}^{bcd}} \frac{\partial}{\partial x^b} F_{cd} = 0 \Rightarrow \partial_{[e} F_{fg]} = 0$$

$\hookrightarrow dF = 0$
(differential form)

* The vector potential A_a : The Gauss-Faraday eqs imply

$$\epsilon^{abcd} \partial_b F_{cd} = 0 \Rightarrow F_{cd} = \partial_c A_d - \partial_d A_c = 2 \partial_{[c} A_{d]}$$

so we can introduce a 4-vector A_a . Note also the

ambiguity $A_a \rightarrow A_a + \partial_a \phi$ that yields the same F_{ab} and

so the same $(\vec{E}, \vec{B}) \Rightarrow$ Gauge symmetry of electromagnetism !!

IV. Lie groups and the Lorentz group

Definition: A group G is a set of elements $g \in G$ with a composition law \cdot such that:
 \hookrightarrow multiplication

* closure: If $g_1, g_2 \in G \Rightarrow g_1 \cdot g_2 \in G$

* associativity: $\forall g_1, g_2, g_3 \in G \Rightarrow g_1 \cdot (g_2 \cdot g_3) = (g_1 \cdot g_2) \cdot g_3$

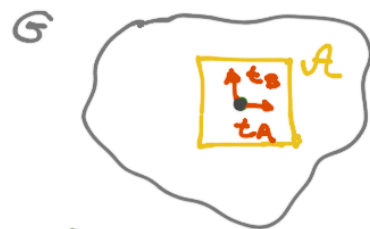
* identity element (e): $\exists e \in G$ such that $e \cdot g = g \cdot e = g$
 $\forall g \in G$

* inverse: $\forall g \in G, \exists g^{-1} \in G$ such that $g \cdot g^{-1} = g^{-1} \cdot g = e$
 \hookrightarrow also a differentiable manifold

Exponential map: Let G be a Lie group and \mathcal{A} its associated Lie algebra. Then there is an exponential map connecting both

Exp: $\mathcal{A} \rightarrow G$

$$X \rightarrow g = e^X = \mathbb{I} + X + \frac{1}{2!} X^2 + \dots = \sum_{k=0}^{\infty} \frac{X^k}{k!}$$



Lie algebra \mathcal{A} : The Lie algebra \mathcal{A} is a vector space

so that

$$X = \sum_{A=1}^{\dim(G)} \theta^A \underbrace{t_A}_{\text{basis elements} \equiv \text{"generators"}}, \quad A=1, \dots, \dim(G)$$

$\underbrace{\text{Real parameters} \equiv \text{Local coordinates}} \quad \quad \quad \underbrace{\dim \text{ of } G = \# \text{ generators}}$

and therefore

$$g = e^{\mathbf{X}} = e^{\sum_{A=1}^{\dim(\mathfrak{g})} \Theta^A t_A} \in G$$

Important: The composition law \cdot in the group becomes

$$e^{\mathbf{X}} \cdot e^{\mathbf{Y}} = e^{\mathbf{Z}} \quad \text{with} \quad \mathbf{Z} = \mathbf{X} + \mathbf{Y} + \frac{1}{2} \underbrace{[\mathbf{X}, \mathbf{Y}]}_{\text{"commutator"}} + \dots$$

↗ extra commutator terms

↓
Baker-Campbell-Hausdorff

Commutators: There is a composition law in the algebra

$$\begin{aligned} \mathcal{A} \times \mathcal{A} &\rightarrow \mathcal{A} \\ [\mathbf{X}, \mathbf{Y}] &\rightarrow \mathbf{Z} \end{aligned}$$

that is antisymmetric and bilinear

$$[\mathbf{X}, \mathbf{Y}] = -[\mathbf{Y}, \mathbf{X}] \quad , \quad [a\mathbf{X} + b\mathbf{Y}, \mathbf{Z}] = a[\mathbf{X}, \mathbf{Z}] + b[\mathbf{Y}, \mathbf{Z}]$$

The algebra \mathcal{A} is totally specified by structure constants defining the commutator between the generators

$$[t_A, t_B] = f_{AB}^C t_C$$

and satisfying the Jacobi identity

$$[\mathbf{X}, [\mathbf{Y}, \mathbf{Z}]] + [\mathbf{Z}, [\mathbf{X}, \mathbf{Y}]] + [\mathbf{Y}, [\mathbf{Z}, \mathbf{X}]] = 0$$

which, taking $\mathbf{X} = t_A$, $\mathbf{Y} = t_B$ and $\mathbf{Z} = t_C$, translates into

$$f_{AD}^E f_{BC}^D + f_{CD}^E f_{AB}^D + f_{BD}^E f_{CA}^D = 0 \Leftrightarrow f_{[CAB}^D f_{CD]}^E = 0$$

Representations : A representation D of G is a mapping of G into linear operators (i.e. matrix operators) so that

- $D(e) = I$ (element with $\Theta^A = 0$)
- $D(g_1 \cdot g_2) = D(g_1) D(g_2)$

Important : The dimension of a representation is the dimension of the vector space with elements σ_i with $i = 1, \dots, N$ on which it acts

$$\sigma^i = [D(g)]^i ; \sigma^j$$

\Rightarrow $\dim(G)$ should not be confused with the dimension of the representation N !!

Important : A group G has various representations D_1, D_2, \dots of different dimension N_1, N_2, \dots .

* **The Lorentz group** : Let us present the Lorentz group as a Lie group.

• $\dim(G) = 6 \Rightarrow$ # of independent rotations in $\mathbb{R}^{1,3}$

• $\Lambda = e^{\frac{1}{2} \Theta^{ab} M_{ab}}$ with $\begin{cases} \Theta^A \equiv \Theta^{ab} = -\Theta^{ba} \\ t_A \equiv M_{ab} = -M_{ba} \end{cases}$

- 3 rotations M_{ij} + 3 boosts M_{0i}
- Commutation relations

$$[M_{ab}, M_{cd}] = \eta_{bc} M_{ad} - \eta_{ac} M_{bd} - \eta_{bd} M_{ac} + \eta_{ad} M_{bc}$$

- Representations:

→ Fundamental (vector): $\dim(D_F) = 4 \in \mathbb{R}$

$$[M_{ab}]^c{}_d = \delta_a^c \eta_{bd} - \delta_b^c \eta_{ad} = 2 \delta_{[a}^c \eta_{b]d}$$

→ Adjoint: $\dim(D_{Adj}) = 6 = \dim(G) \in \mathbb{R}$

$$\begin{aligned} [M_{ab}]^{ef}{}_{cd} &= \eta_{ac} \delta_b^e \delta_d^f - \eta_{bc} \delta_a^e \delta_d^f + \eta_{ad} \delta_b^f \delta_c^e - \eta_{bd} \delta_a^f \delta_c^e \\ &= -f_{abcd}{}^{ef} \quad [\text{in terms of structure constants}] \end{aligned}$$

⇒ Structure constants $f_{AB}{}^C = f_{abcd}{}^{ef}$ with

$$f_{abcd}{}^{ef} = 8 \eta_{c[b} \delta_{a]}^e \delta_{d]}^f$$

→ Spinorial:

$$[M_{ab}]^\alpha{}_\beta = \frac{1}{4} [\gamma_{ab}]^\alpha{}_\beta$$

with $\gamma_{ab} = \gamma_a \gamma_b - \gamma_b \gamma_a = [\gamma_a, \gamma_b]$ in terms of γ -matrices.

▶ Spinorial Weyl : $\dim(D_W) = 2^{\frac{4}{2}-1} = 2 \in \mathbb{C}$
 $(d=1,2)$

$$\gamma_a = (\mathbb{I}_{2 \times 2}, \underbrace{\sigma_1, \sigma_2, \sigma_3}_{\text{Pauli matrices}})$$

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

▶ Spinorial Dirac: $\dim(D_D) = 2^{\frac{4}{2}} = 4 \in \mathbb{C}$
 $(d=1, \dots, 4)$

$$\gamma_0 = \begin{pmatrix} \mathbb{I}_2 & 0 \\ 0 & -\mathbb{I}_2 \end{pmatrix}, \quad \gamma_i = \begin{pmatrix} 0 & \sigma_i \\ -\sigma_i & 0 \end{pmatrix}$$

▶ Spinorial Majorana : $\dim(D_M) = 2^{\frac{4}{2}} = 4 \in \mathbb{R}$
 $(d=1, \dots, 4)$

$$\gamma_0 = \begin{pmatrix} 0 & \sigma_2 \\ \sigma_2 & 0 \end{pmatrix}, \quad \gamma_1 = \begin{pmatrix} i\sigma_3 & 0 \\ 0 & i\sigma_3 \end{pmatrix}, \quad \gamma_2 = \begin{pmatrix} 0 & -\sigma_1 \\ \sigma_1 & 0 \end{pmatrix}, \quad \gamma_3 = \begin{pmatrix} -i\sigma_1 & 0 \\ 0 & -i\sigma_1 \end{pmatrix}$$

• Particles in Minkowski space-time : They transform under the above representations of the Lorentz group

- Bosons $\begin{cases} s=0 : \Phi \\ s=1 : A_a \\ s=2 : \eta_{ab} \end{cases} \Rightarrow \text{Integer spin } s=0, 1, 2$

- Fermions $\begin{cases} s=\frac{1}{2} : \psi_\alpha \\ s=\frac{3}{2} : \chi_{\alpha\beta} \end{cases} \Rightarrow \text{Half-integer spin } s=\frac{1}{2}, \frac{3}{2}$

V. Classical fields in Minkowski space-time

Let us consider a classical field $\phi(x)$ of any of the types discussed before. And let us consider an action

$$S = \int \underbrace{\mathcal{L}(\phi, \partial_a \phi)}_{\text{Lagrangian density}} d^4x$$

* Equation of motion (E.O.M) :

$$\delta S = 0 \Rightarrow \text{Arbitrary variation } \delta \phi$$

$$\Rightarrow \frac{\delta S}{\delta \phi} = 0 \Leftrightarrow \frac{\partial \mathcal{L}}{\partial \phi} - \partial_a \left[\frac{\partial \mathcal{L}}{\partial (\partial_a \phi)} \right] = 0$$

"Euler-Lagrange equations"

NOTE: Two Lagrangians differing on a divergence $\partial_a T^a$ yields the same E.O.M.

* Conserved current: J^a is a conserved current if

$$\partial_a J^a = 0 \Rightarrow Q = \int J^{(0)} d^3x \equiv \text{Conserved charge}$$

* Symmetry: Let us consider an infinitesimal δ_ϵ transformation on coordinates and/or fields with continuous constant parameter ϵ

$$x'^a = x^a + \delta_\epsilon x^a$$

$$\phi'(x') = \phi(x) + \delta_\epsilon \phi$$

If $\delta_\epsilon S = 0 \Rightarrow$ Symmetry !!

• Acting with a general transformation on fields

$$\delta S = \int \partial_a J^a d^4x \quad \rightarrow \text{linear dependence on } \epsilon$$

with the so-called "Noether current"

$$J^a = \frac{\partial \mathcal{L}}{\partial(\partial_a \phi)} \delta \phi - \left[\frac{\partial \mathcal{L}}{\partial(\partial_a \phi)} (\partial_b \phi) - \delta_b^a \mathcal{L} \right] \delta x^b$$

Then, if the transformation is a symmetry, one has

$$\delta \mathcal{L} = 0 \quad \Rightarrow \quad \partial_a \mathcal{J}^a = 0$$

* Noether Theorem: If a Lagrangian has a continuous symmetry $\Rightarrow \exists$ a current associated with that symmetry which is conserved provided the EOM holds.

* Types of transformations in SR [Poincaré sym]

i) Internal: $\delta \phi \neq 0$, $\delta x^a = 0$

ii) Translations: $\delta \phi = 0$, $\delta x^a = \epsilon^a$

iii) Lorentz: $\delta \phi \neq 0$, $\delta x^a = \theta^a_b x^b$

with

$$\Lambda^a_b = e^{\underbrace{\frac{1}{2} \theta^{cd} [M_{cd}]^a_b}_{\text{algebra } \mathfrak{SO}(1,3)}} \in \text{SO}(1,3)$$

$$\downarrow$$

$$[M_{cd}]^a_b = 2 \delta_{[c}^a \eta_{d]b}$$

Example : Translations $x'^a = x^a + \epsilon^a \Rightarrow \delta x^a = \epsilon^a$

$$\Rightarrow J^a = -T^a_b \epsilon^b \quad \delta \phi = 0$$

$$\text{with } T^{ab} = \frac{\partial \mathcal{L}}{\partial (\partial_a \phi)} \partial^b \phi - \eta^{ab} \mathcal{L}$$

↳ Energy-momentum tensor

Then, covariance under translations requires

$$\partial_a J^a = -(\partial_a T^{ab}) \epsilon_b = 0$$

↳ arbitrary

$$\Rightarrow \boxed{\partial_a T^{ab} = 0}$$

[conserved energy-momentum tensor]

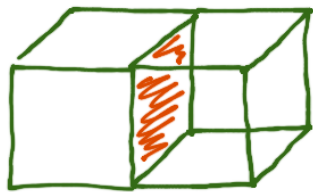
and the conserved quantities are

$$P^a = \int T^{0a} d^3x \quad [\text{energy and momentum}]$$

VI. Perfect fluid in Minkowski space-time

In many areas of physics matter is modelled as a **perfect fluid**. Let us introduce the various concepts involved in its definition.

* **Fluid**: Continuous medium that can be divided into "fundamental elements" with a **contact surface**



viscosity [parallel to \equiv]
pressure [perpendicular to \equiv]

for which $\text{viscosity} \ll \text{pressure}$.

* **Energy-momentum tensor**: Any continuous medium has its energy and momentum codified into an energy-momentum tensor T^{ab}

T^{00} : Energy flux through a $t = \text{cst}$ surface

T^{0j} : Energy flux through a $x^j = \text{cst}$ surface

T^{i0} : Momentum flux through a $t = \text{cst}$ surface

T^{ij} : Momentum flux through a $x^j = \text{cst}$ surface

$\approx > T^{ii} \equiv \text{Pressure}$

$T^{ij} (i \neq j) \equiv \text{Viscosity}$

NOTE: If there is no special space-time point in the fluid
(translation invariant) then $\partial_a T^{ab} = 0$

[energy-momentum conservation]
[fluid is a closed system]

* **Momentarily Inertial Frame (MIF)** : It is defined as such coordinate system for which the elements in the fluids are in rest

$$u_{\text{MIF}}^a = (c, \vec{0})$$

* **Perfect fluid** : It is a fluid for which, in the MIF,

$$T^{ij} (i \neq j) = T^{i0} = T^{0j} = 0$$

so that

$$T_{\text{MIF}}^{ab} = \begin{bmatrix} \rho & & & \\ & p & & \\ & & g^{ij} & \\ & & & \end{bmatrix}$$

energy density

pressure

In an arbitrary Lorentz frame one has

$$T^{ab} = P \eta^{ab} + (P + p) \frac{u^a u^b}{c^2}$$